

Dimensionality Reduction Techniques for Statistical Analysis and Modeling in Medical Imaging

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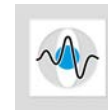
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Agenda

- Introduction
 - Dimensionality Reduction
 - Statistical Analysis and Modeling
 - Nomenclature
- Linear Dimensionality Reduction
 - Principal Component Analysis (PCA)
 - Multidimensional Scaling (MDS)
 - Applications
- Non-linear Dimensionality Reduction
 - Kernel Principal Component Analysis (KPCA)
 - Manifold Learning and Graph-Based Methods
 - Applications



Motivation

- Dimensionality Reduction
- Statistical Analysis and Modeling
- Nomenclature



Dimensionality Reduction

- Curse of dimensionality
 - No statistical significance due to sparse sampling
 - Distance metrics not meaningful
 - Computational burden
- Visualization
 - Intuitive feel what the data looks like
 - Analysis of machine learning algorithms
- Underlying forces
 - How are samples created?
 - Important features and structures
 - Removal of misleading features



Statistical Analysis and Modeling

- Statistical analysis
 - **Describe, understand** and **predict** a population based on sample datasets (inference)
 - Characterize data in a short and compact form
 - *Out-of-sample* problem
- Statistical modeling
 - **Reconstruction** of a complex entity from a compact statistical description
 - *Pre-image* problem

Underlying statistical model?

Nomenclature

- High-dimensional (mean-centered) input points

$$\{\mathbf{x}_i\}_{i=1}^n, \mathbf{x}_i \in \mathbb{R}^D, \sum_i \mathbf{x}_i = \mathbf{0}$$

- Low-dimensional output points

$$\mathbf{y}_i \in \mathbb{R}^d, d \ll D$$

- Matrix notation

$$\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n] \in \mathbb{R}^{D \times n}$$

- Inner products

$$\mathbf{x}_i^\top \mathbf{x}_j = \langle \mathbf{x}_i, \mathbf{x}_j \rangle = (\mathbf{x}_i \cdot \mathbf{x}_j)$$

Nomenclature

- *Out-of-sample* problem
 - For an **unseen** sample $\hat{x} \in \mathbb{R}^D$, $\notin \{x_i\}_{i=1}^n$ what is its corresponding low-dimensional representation $\hat{y} \in \mathbb{R}^d$?
 - This may be a non-trivial task...
- *Pre-image* problem
 - Given an **arbitrary** low-dimensional representation $\hat{y} \in \mathbb{R}^d$, what is the corresponding vector $\hat{x} \in \mathbb{R}^D$ in input space?
 - For many dimensionality reduction techniques, the exact pre-image simply does not exist!



Linear Dimensionality Reduction

- Principal Component Analysis (PCA)
- Multidimensional Scaling (MDS)
- Applications

Principal Component Analysis (PCA)

- Find the directions (i) along which the data has **maximum variance** and (ii) the **relative importance** of these directions
- Minimum reconstruction error:

$$\mathcal{J}_{\text{PCA}} = \sum_i \left\| \mathbf{x}_i - \sum_{j=1}^d (\mathbf{x}_i \cdot \mathbf{e}_j) \mathbf{e}_j \right\|^2 = \sum_i \|\mathbf{x}_i - \mathbf{E}\mathbf{y}_i\|^2$$

$$\text{subject to } (\mathbf{e}_i \cdot \mathbf{e}_j) = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

- Solution given by Eigen-decomposition of the covariance matrix

$$\mathbf{C} = \frac{1}{n} \sum_i \mathbf{x}_i \mathbf{x}_i^\top = \mathbf{E} \mathbf{\Lambda} \mathbf{E}^\top, \quad \mathbf{\Lambda} = \text{diag}(\lambda_1, \dots, \lambda_D)$$

Principal Component Analysis (PCA)

- *Out-of-sample* problem
 - Principal axes E derived from the training set $\{x_i\}_{i=1}^n$
 - For an unseen sample $\hat{x} \in \mathbb{R}^D$ its low-dimensional representation is:

$$\hat{y} = E^\top \hat{x}$$

- *Pre-image* problem
 - For an arbitrary low-dimensional representation $\hat{y} \in \mathbb{R}^d$ the corresponding vector in input space is

$$\hat{x} = E\hat{y}$$

- This follows from the orthonormality of E

This is straight-forward...

Principal Component Analysis (PCA)

- PCA requires the data to lie on a d -dimensional **linear subspace**
 - This will introduce some error in practice
 - Will definitely fail for curved manifolds

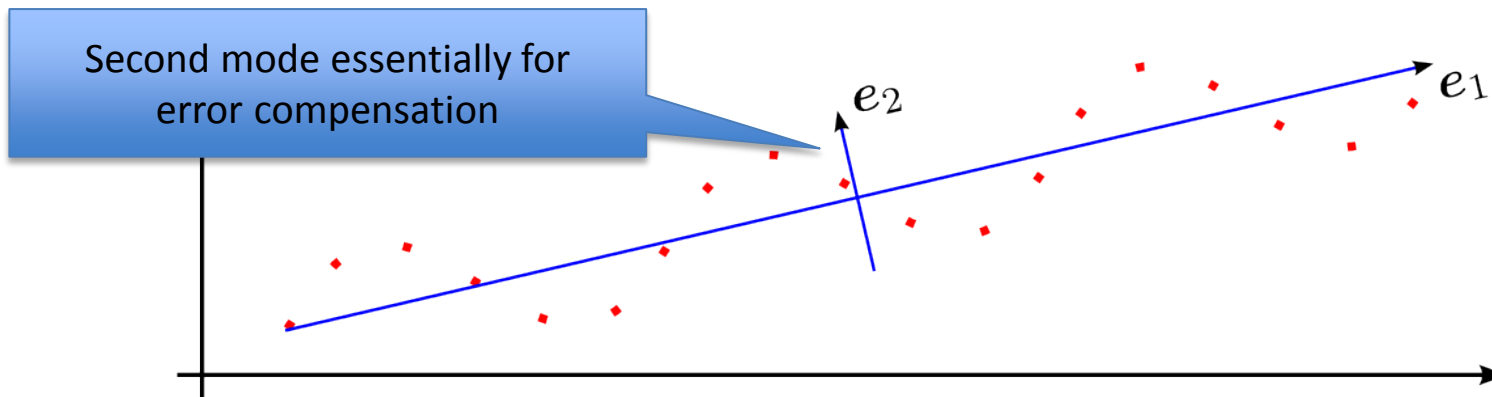


Figure: PCA applied to samples drawn from a sine curve.

Principal Component Analysis (PCA)

- PCA yields global modes of variation
 - Sparsity is sacrificed for the sake of variance maximization
 - Remedies: Factor-Rotations [1], Sparsity-Regularization [2,3]

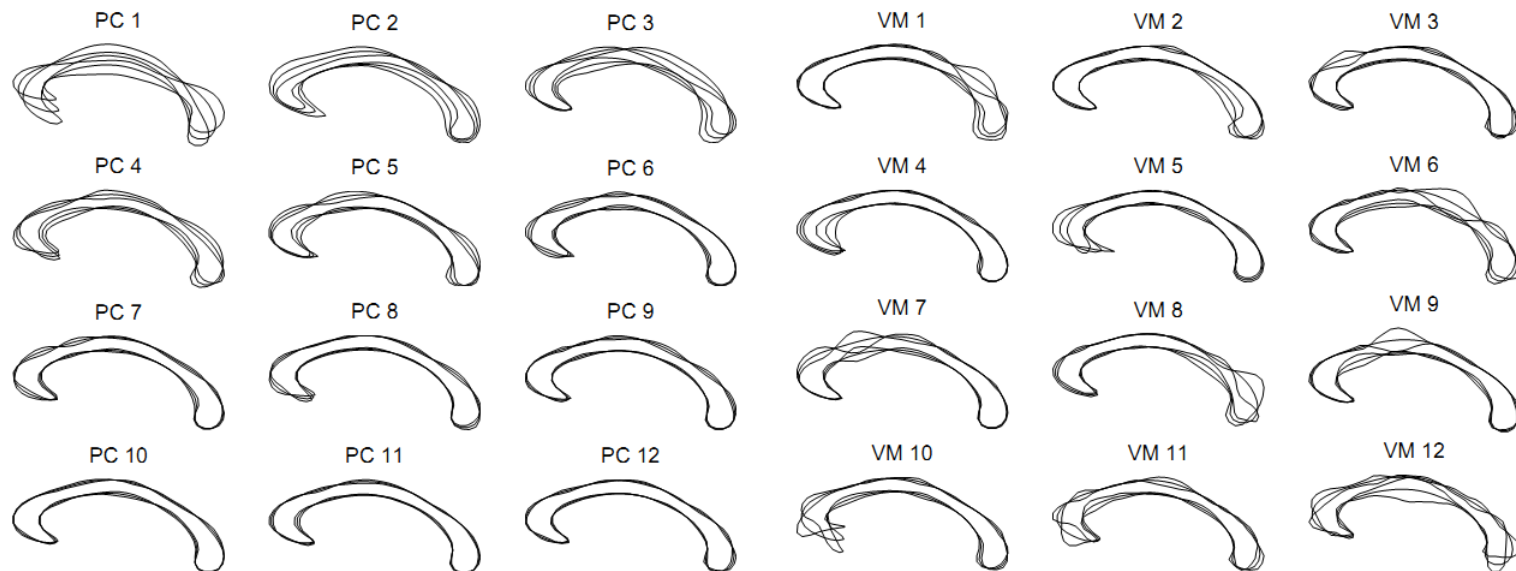


Figure: PCA and varimax rotations applied to corpus callosum annotations [1].

Multidimensional Scaling (MDS)

- Compute low-dimensional representation that **preserves mutual inner products**
 - Pairwise distances (equals PCA)
 - Mutual angles
 - Generalized metrics

- Objective function

$$\mathcal{J}_{\text{MDS}} = \sum_{i,j} (\mathbf{x}_i \cdot \mathbf{x}_j - \mathbf{y}_i \cdot \mathbf{y}_j)^2$$

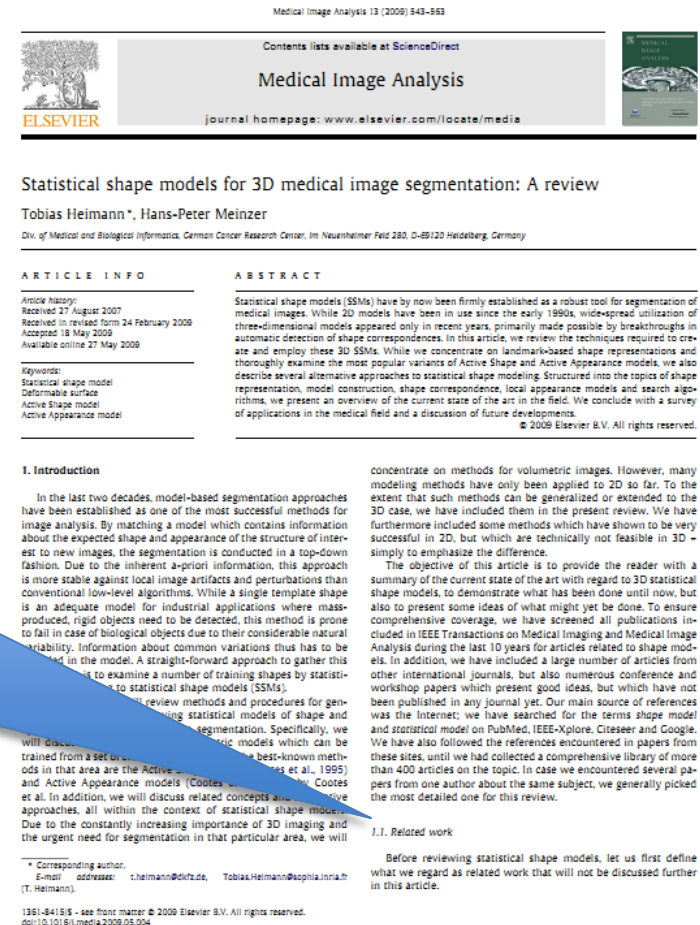
- Solution given by spectral decomposition of the Gram matrix

$$G_{i,j} = \mathbf{x}_i \cdot \mathbf{x}_j$$

Applications

- Statistical shape models for 3D medical image segmentation

On the one hand, the PCA approach employed by the vast majority of studies unquestionably has its weaknesses: A number of modeled shapes will certainly not feature Gaussian distributions and the linear approximation model will be suboptimal. On the other hand, PCA is fairly robust to the input data distribution and generally just works.



Heimann T, Meinzer HP.

Statistical shape models for 3D medical image segmentation: A review

In: Medical Image Analysis. Vol. 13(4), pp. 543-563, 2009

Applications

- Model-based segmentation

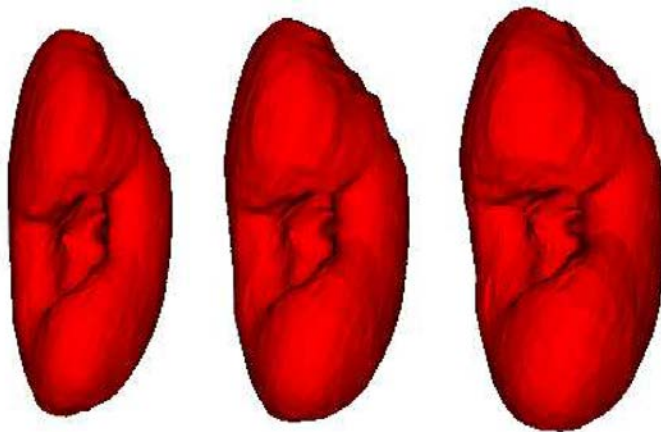


Figure: First mode of variation.

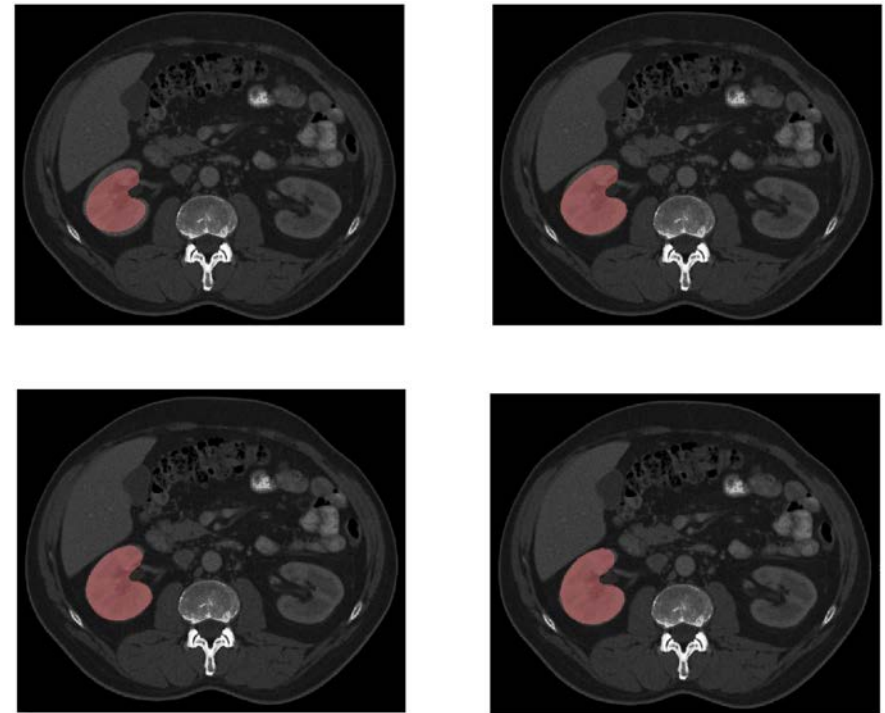


Figure: Kidney segmentation using ASMs.

Spiegel M, Hahn D, Daum V, Wasza J, Hornegger J.

Segmentation of kidneys using a new active shape model generation technique based on non-rigid image registration

In: Computerized Medical Imaging and Graphics. Vol. 33, pp. 29-39, 2009

Applications

- 4-D shape priors for respiratory motion management

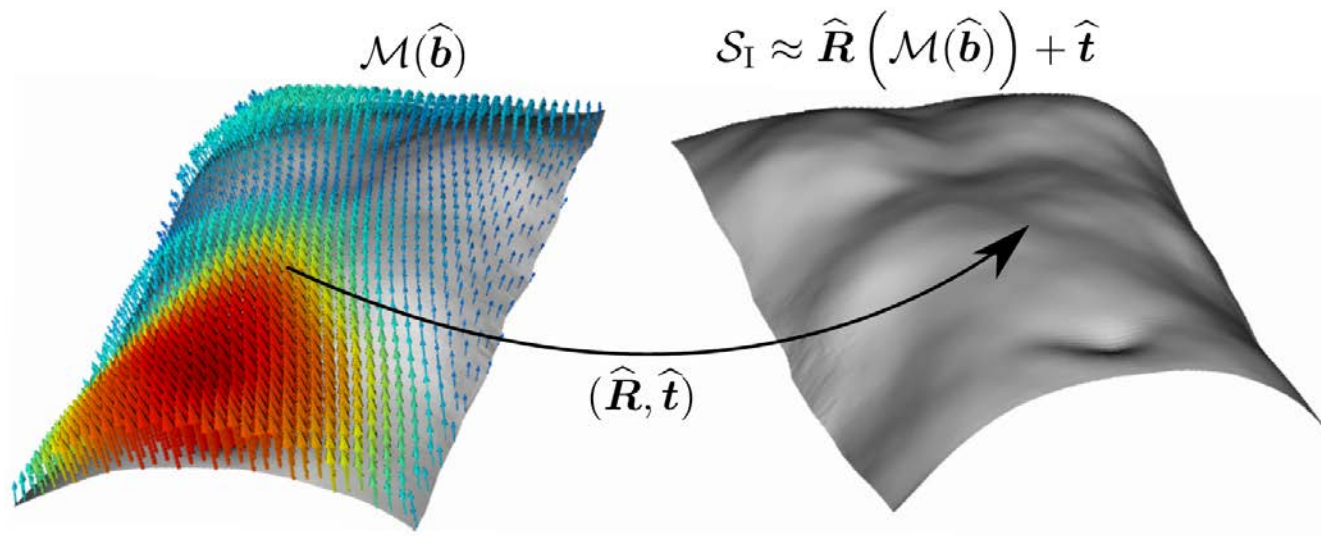


Figure: Motion compensated patient positioning

Wasza J, Bauer S, Hornegger J.

Real-time Motion Compensated Patient Positioning and Non-Rigid Deformation Estimation using 4-D Shape Priors

In: MICCAI 2012, accepted for publication

Applications

- Respiratory model of anatomical motion

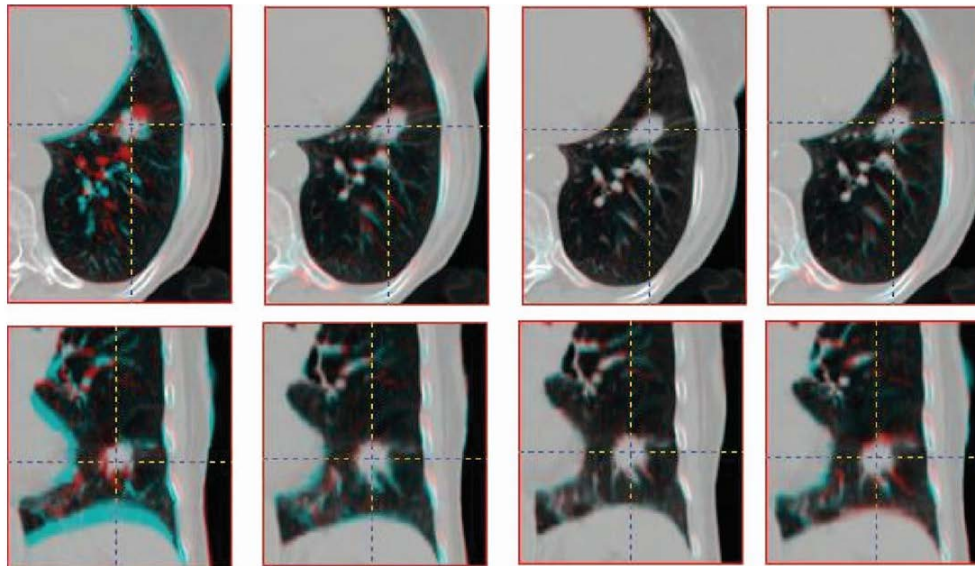


Figure: Actual CT and reconstructed volume.

Zhang Q, Pevsner A, Hertanto A, Hu Y, Rosenzweig K, Ling C, Mageras G.

A patient-specific respiratory model of anatomical motion for radiation treatment planning

In: Medical Physics. Vol. 34(12), pp. 4772-4781, 2007



Non-linear Dimensionality Reduction

- Kernel Principal Component Analysis (KPCA)
- Manifold Learning and Graph-Based Methods
- Applications

Kernel Principal Component Analysis (KPCA)

- Basic idea [4]: compute PCA in a **feature space** $\phi(x_i) \in \mathcal{H}$ instead of the original input space $x_i \in \mathbb{R}^D$
 - In general: $\mathcal{H} = \mathbb{R}^\infty$
 - Kernel trick: $\phi(x_i) \cdot \phi(x_j) = k(x_i, x_j)$

- Covariance matrix in feature space \mathcal{H}

$$C = \frac{1}{n} \sum_i \phi(x_i) \phi(x_i)^\top$$

- This is equivalent to non-linear MDS
 - Kernel matrix contains generalized inner products in feature space
 - Spectral decomposition of the Gram matrix in feature space

Kernel Principal Component Analysis (KPCA)

- Eigendecomposition of the kernel matrix $K_{i,j} = k(x_i, x_j)$

$$K = E\Lambda E^\top = E\Lambda^{\frac{1}{2}} \left(E\Lambda^{\frac{1}{2}}\right)^\top$$

$$E = [e_1, \dots, e_n] \text{ , } \Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$$

- Note that the number of modes equals the number of samples! This is in contrast to conventional PCA.

- Projection on the p -th Eigenvector V^p

$$y_i^p = V^p \cdot \phi(x_i) = \sqrt{\lambda_p} e_i^p$$

- Note that we assume the data to be mean-centered in feature space. This in general not valid, for details see [4].

Kernel Principal Component Analysis (KPCA)

- *Out-of-sample* problem
 - Not as easy as with conventional PCA
 - Related to the Nyström extension [5]

$$\hat{\mathbf{y}}^p = \mathbf{V}^p \cdot \phi(\hat{\mathbf{x}}) = \frac{1}{\sqrt{\lambda_p}} \sum_{i=1}^n \mathbf{e}_i^p (\phi(\mathbf{x}_i) \cdot \phi(\hat{\mathbf{x}})) = \frac{1}{\sqrt{\lambda_p}} \sum_{i=1}^n \mathbf{e}_i^p k(\mathbf{x}_i, \hat{\mathbf{x}})$$

- *Pre-image* problem
 - In feature space like regular PCA
 - From feature space to input space an ill-posed problem
 - Usually approximated by minimizing an error function [5]

$$\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{V} \phi(\mathbf{x}) - \hat{\mathbf{y}}\|^2$$

Kernel Principal Component Analysis (KPCA)

- Choosing the kernel function
 - Radial basis functions (RBF)
 - Polynomial kernels
 - Linear functions
 - See also Kernel-SVM and Kernel-SVR
- Parameters
 - Highly depend on the problem
 - Slightly different parameters usually produce complete different results

There is no rule which kernel to choose and how to select its parameters!

Kernel Principal Component Analysis (KPCA)

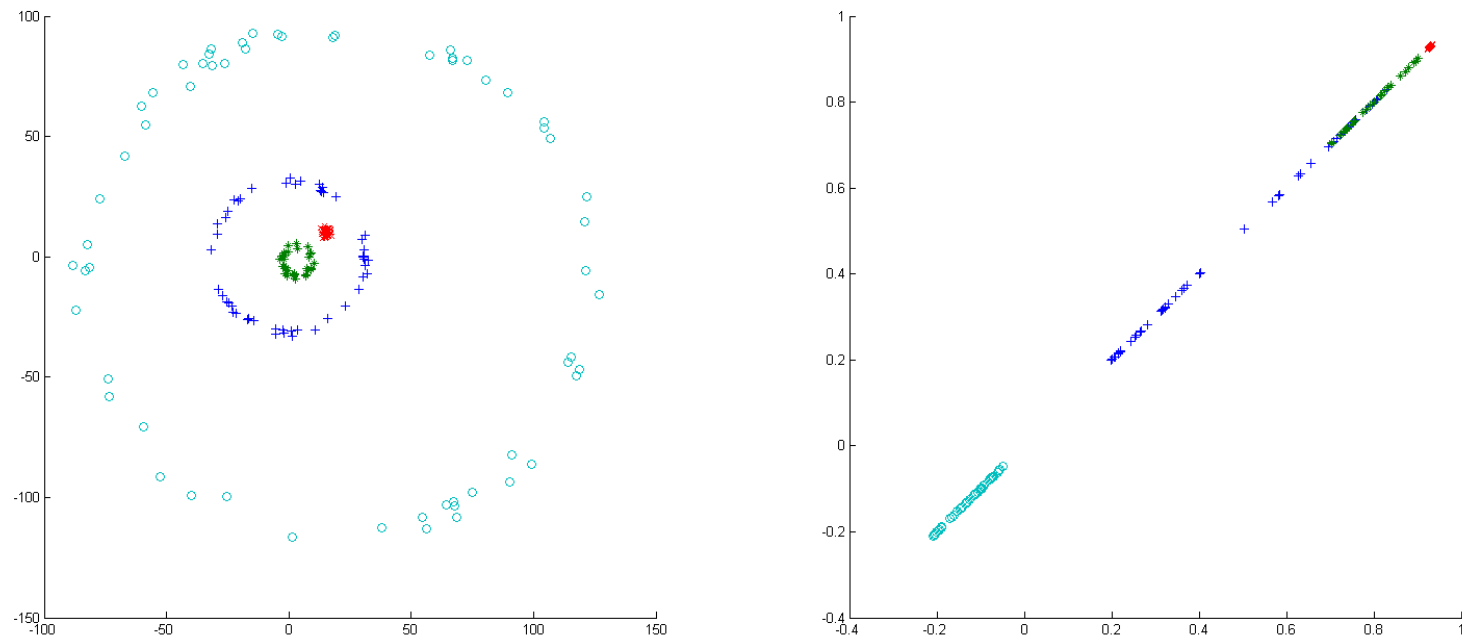


Figure: Dimensionality reduction using KPCA.

Manifold Learning and Graph-Based Methods

- Basic idea: duplicate the behavior of PCA on **manifolds** instead of linear subspaces
- Manifolds:
 - Low-dimensional structure embedded in a high-dimensional space
 - Geodesic distances vs. euclidean distances

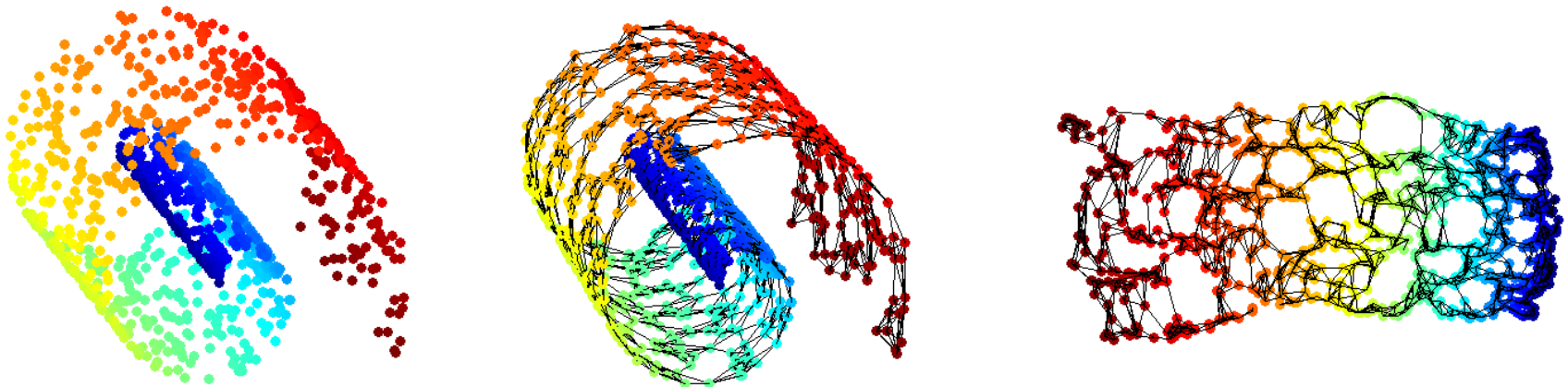


Figure: The swissroll manifold. Left: original data. Middle: connected data. Right: unfolded.

Manifold Learning and Graph-Based Methods

- Multitude of approaches (see [6,7] for overviews)
 - Isomap
 - Locally Linear Embedding
 - Laplacian Eigenmaps
 - Maximum Variance Unfolding
 - ...
- Key issues
 - Discrete manifold approximations (graphs)
 - Geodesic distances (shortest paths)

Manifold Learning: Isomap

- Idea: Preserve distances between input patterns **as measured along the manifold from which they were sampled** → Geodesic distances

- Estimation of geodesic distances

- k -nearest neighbor graph $\mathcal{G}_k = (\mathcal{V}, \mathcal{E}_k)$

$$\mathcal{V} = \{\mathbf{x}_i\}_{i=1}^n, \quad \mathcal{E}_k = \{\|\mathbf{x}_i - \mathbf{x}_j\| \mid \mathbf{x}_j \in \mathcal{N}^k(\mathbf{x}_i)\}$$

- Geodesic distance matrix

$$D_{i,j} = \text{ShortestPath}(\mathcal{G}^k, \mathbf{x}_i, \mathbf{x}_j)$$

- Classical MDS on the geodesic distances

$$\mathcal{J}_{\text{IsoMDS}} = \sum_{i,j} (D_{i,j} - \mathbf{y}_i \cdot \mathbf{y}_j)^2$$

Manifold Learning and Graph-Based Methods

- *Out-of-sample* problem
 - Depends on the method
 - Often related to the Nyström extension
- *Pre-image* problem
 - Depends on the method
 - Closely related to the *out-of-sample* problem
- Common problems
 - All algorithms require a neighborhood size
 - Theoretical performance results often not available
 - Target dimensionality must be specified in general
 - Do real world data exhibit manifold structures?

Applications

- Image-based breathing gating

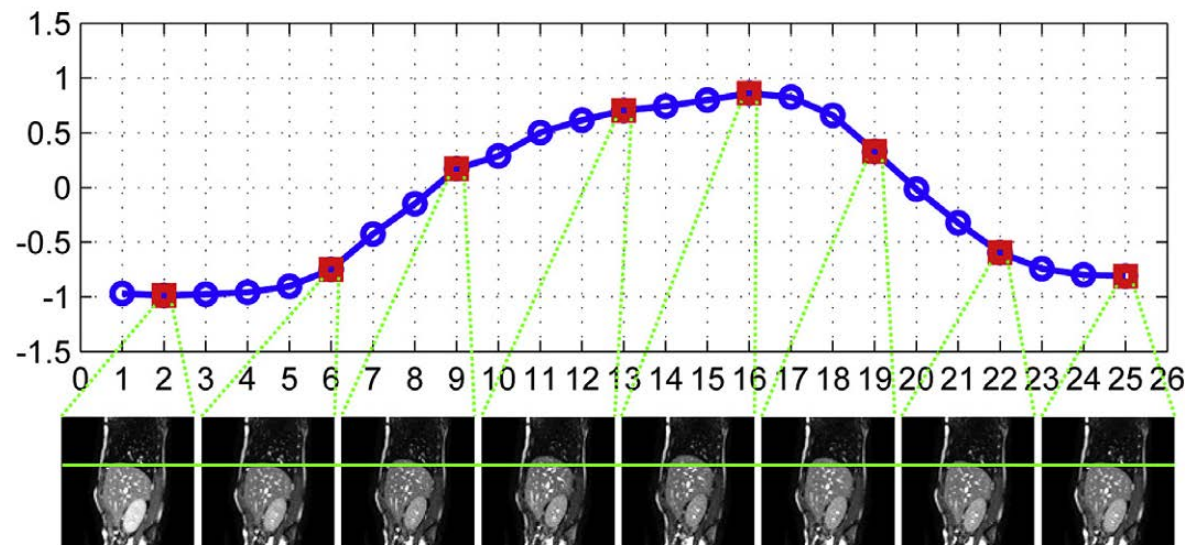


Figure: Image-based breathing signal obtained by manifold learning.

Wachinger C, Yigitsoy M, Rijkhorst E, Navab N.

Manifold learning for image-based breathing gating in ultrasound and MRI

In: Medical Image Analysis, Vol. 16(4), pp.806-818, 2012

Applications

- Registration, Segmentation and Classification

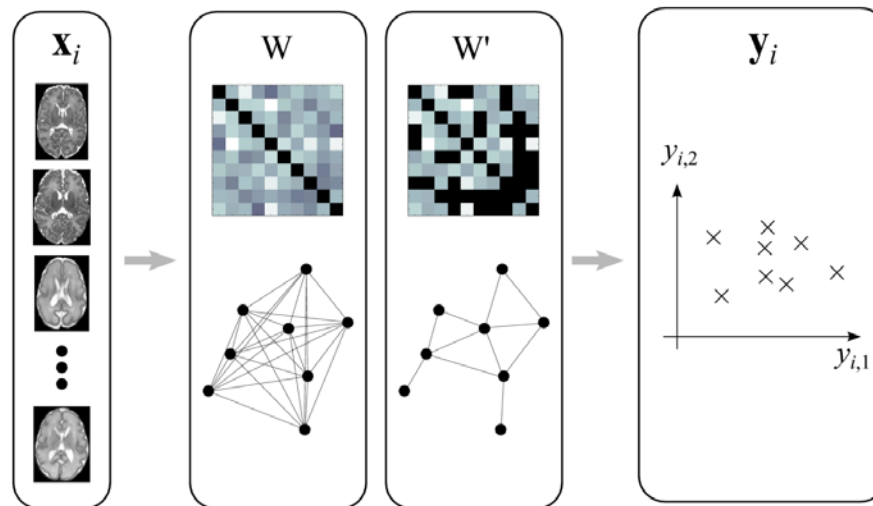


Figure: Schematic overview of manifold learning in medical imaging.

Aljabar, P, Wolz R, Rueckert D.

Manifold Learning for Medical Image Registration, Segmentation and Classification

In: Machine Learning in Computer-Aided Diagnosis: Medical Imaging Intelligence and Analysis, 2012



Bibliography

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In: Proc SPIE. Vol. 6144, 2006

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Sparse Principal Component Analysis

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An inverse power method for nonlinear eigenproblems with applications in 1-spectral clustering and sparse PCA

In: Advances in Neural Information Processing Systems, 2010

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Nonlinear Component Analysis as a Kernel Eigenvalue Problem

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Algorithms for manifold learning

Technical Report CS2008-0923, Univ. of California, 2005

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In: Semi-Supervised Learning, pp. 293-308, 2006