

Stromer, Daniel 14.04.2016 Pattern Recognition Lab (CS 5)





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Outline



- Introduction
- Materials and Methods
 - Scan Modes and Field-of-View Enlargement
 - C-arm CT 3-D Reconstruction
- Results
- Discussion and Outlook



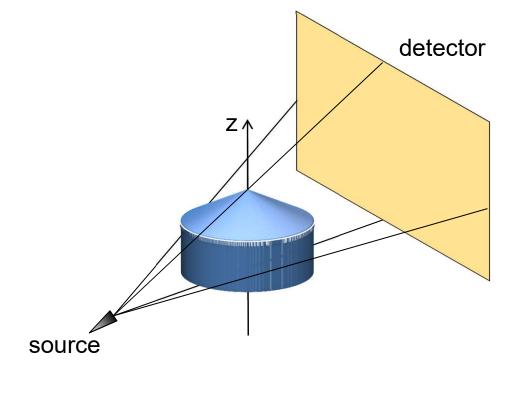
- 3-D imaging uses Short- and Large Volume Scan
- Patient may be still too large to be completely covered
- Find method to enlarge the detector's field-of-view in lateral direction



Materials and Methods





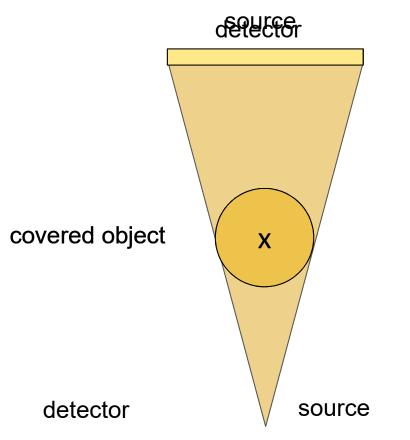


Cone Beam Geometry





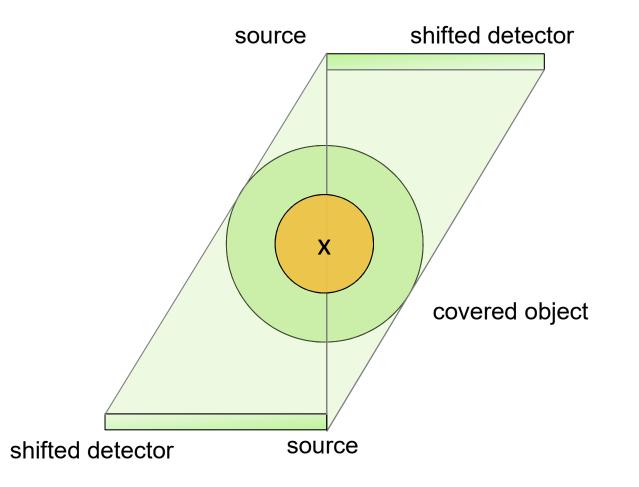
• 200 degree circular scan (180 degrees + fan angle)







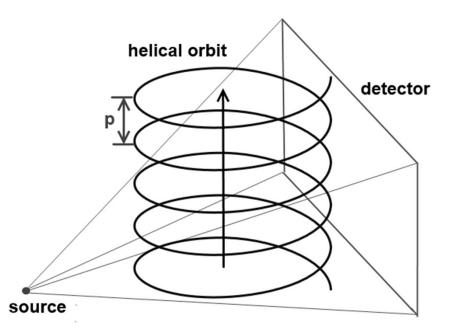
• 360 degree circular scan with shifted detector

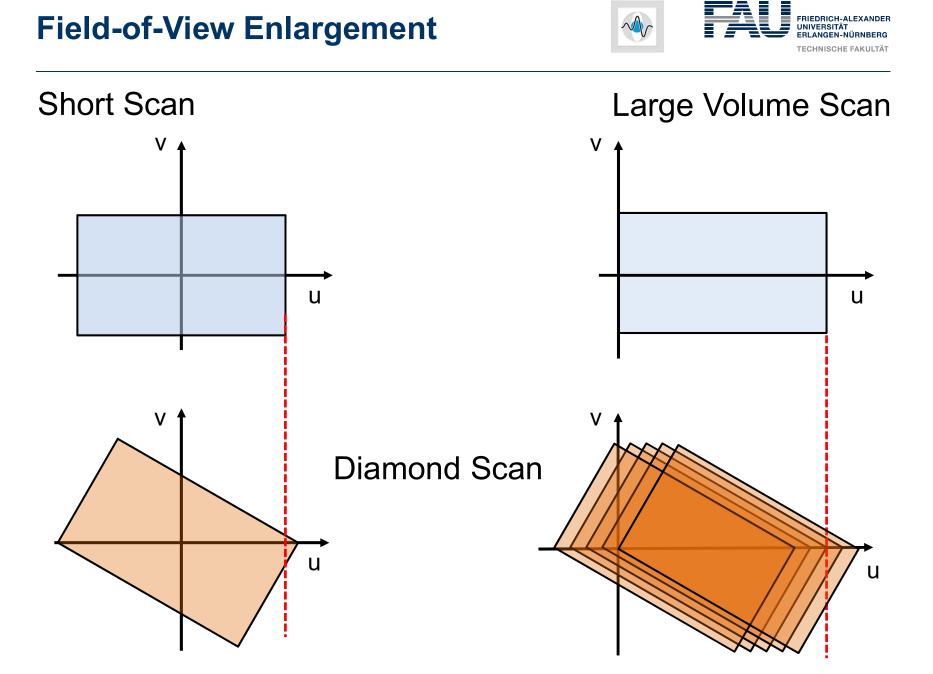


Helical Large Volume Scan



- Similar to Large Volume Scan
- Helical orbit with pitch p
- Increased axial coverage







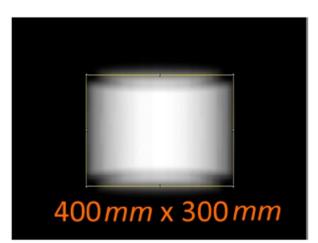
- CONRAD Framework used for simulations
 - Detector: 400 mm x 300 mm, SID 1200 mm, SOD 785 mm
- Implemented data completeness estimation
 - 1. Discrete sampling of the unit sphere in vectors \boldsymbol{u} #points sampled on the sphere: N_u
 - 2. Computation of data completeness in terms of voxel-wise Radon sphere coverage #unit vectors satisfying the condition: N_c
 - 3. Resulting Radon sphere coverage

 $c = \frac{N_c}{N_u} \cdot 100\%$

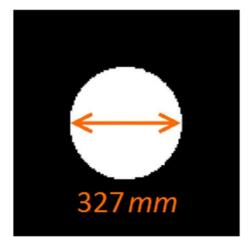
Short Scan coverage

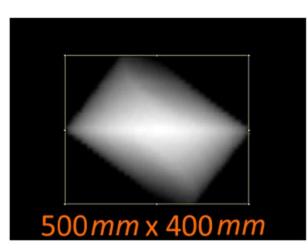






Short Scan Radon sphere coverage and forward projection of the coverage volume

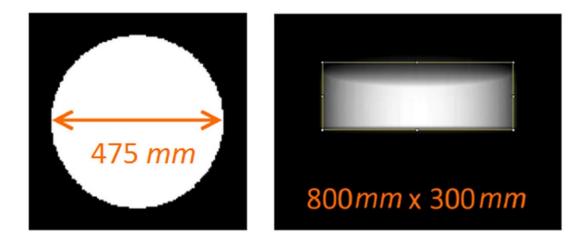




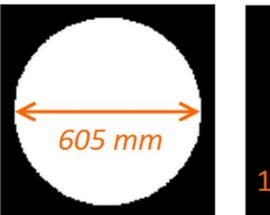
Diamond Short Scan Radon sphere coverage and forward projection of the coverage volume

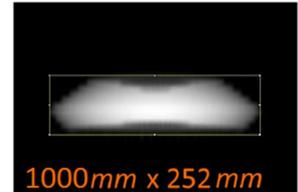
Large Volume Scan (LVS) coverage





Large Volume Scan Radon sphere coverage and forward projection of the coverage volume

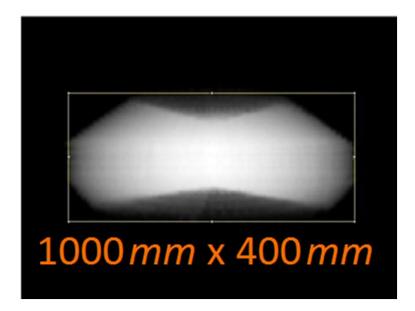




Diamond LVS Scan Radon sphere coverage and forward projection of the coverage volume

Helix coverage





Forward projected volume coverage for Helix Diamond Large Volume Scan



	Radon sphere coverage			
Scan Mode	Standard [mm]	Diamond [mm]	Plus [mm]	Plus [%]
Short Scan	261	327	66	25.3
Large Volume Scan	475	605	130	27.3
Helix LVS	475	605	130	27.3

- Coverage increased by 25.3 % for the Short Scan and about 27.3 % for the Large Volume Scans
- Using a helical trajectory compensates the axial loss



C-arm CT 3-D Reconstruction



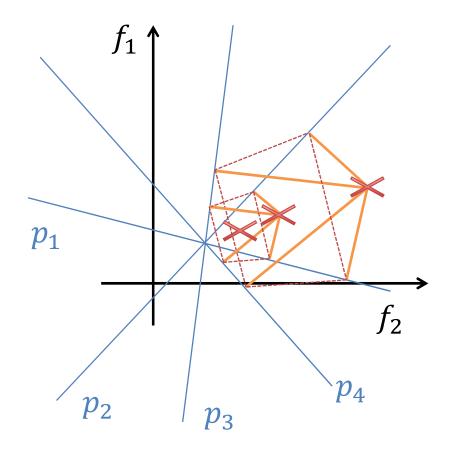
- Inverse problem of Radon transform is reformulated as system of equations:
 - $p = \mathbf{R} \cdot f(\mathbf{v})$ \mathbf{v} : voxelp: measured data \mathbf{R} : Radon transform
- Minimization of objective function (SSD):

 $\min \left| \left| \boldsymbol{R} \cdot f(\boldsymbol{v}) - p \right| \right|_2^2$

SART Reconstruction



- Compute orthogonal projections of the current approximation to the hyperplanes
- Compute the centroid and use it for the next iteration





TV-based reconstruction:

- Aim: Raw data fidelity and piecewise constant output
- TV is based on the Compressed Sensing theory

$$\min ||\psi f(\boldsymbol{v})||_{1} \text{ subject to } \min ||\boldsymbol{R}f(\boldsymbol{v}) - \boldsymbol{p}||_{2}^{2} < \epsilon$$

- ψ is a sparsifying transformation of f(v)
- ϵ denotes the raw data consistency (similarity measure)



Results





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Configuration



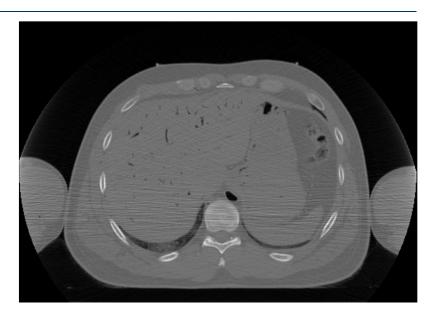
• Visual Human Project data set

Scaling: waist circumference 130 cm (\leq 5% of US American population) Transversal misalignment of 10% (32mm) was assumed

• Error measurement

$$\text{RMSE} = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (f_i(v) - \hat{f}_i(v))^2}$$

• Reconstructed with SART and eTV





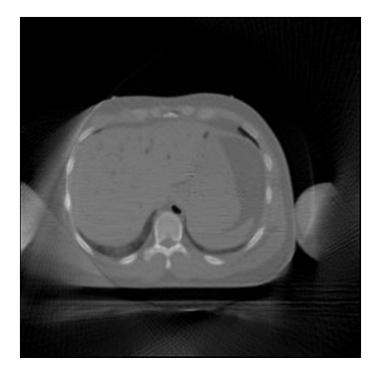
Scan Mode	RMSE _{SART}	RMSE _{eTV}
Short Scan	0.2134	0.1370
Diamond Short Scan	0.2026	0.1242
Standard LVS	0.0608	0.0549
Diamond LVS	0.0322	0.0217
Helical LVS	0.0641	0.0488
Helical Diamond LVS	0.0229	0.0151

eTV lowers the RMSE compared to SART by 29.1 %

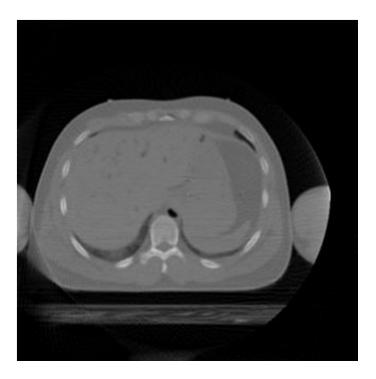
VHP eTV Reconstructions



Central Slices (z=15 of 30)



Large Volume Scan

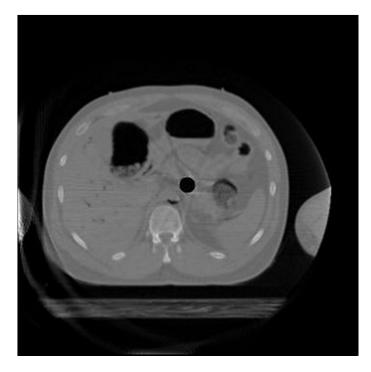


Diamond Large Volume Scan

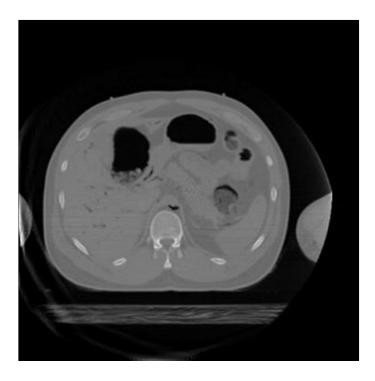
VHP eTV Reconstructions



Outmost Slices (z=30 of 30)



Diamond Large Volume Scan



Helix Diamond Large Volume Scan



- Coverage gain with presented method:
 - Short Scan 25 %, LVS: 27 % Helix: axial gain
- Reconstruction:
 - eTV lowers RMSE compared to SART by 29 %

But:

- Only coverage > 0.9 was considered
- Different detector settings may fit better
- Other eTV parameters may increase quality



Thank you very much for your attention

