

# Quality Guided Image Denoising for Low-Cost Fundus Imaging

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# Outline

Introduction – Denoising for (Low-cost) Fundus Imaging

Quality Guided Denoising Method

Experiments and Results

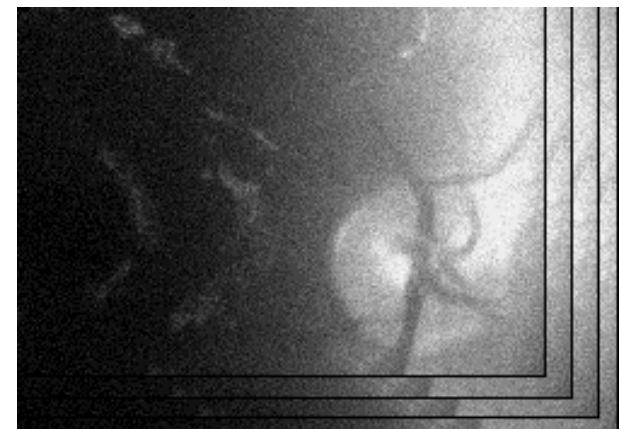
Summary and Conclusion



# Introduction – Denoising for (Low-cost) Fundus Imaging

# Motivation

- Fundus imaging: modality to capture the human eye fundus
    - High-resolution color image, low noise level
    - Expensive and not mobile
  - **Our goal:** low-cost camera system
    - Cheap and mobile
    - Problems: low-resolution grey-scale images, illumination artifacts, **poor noise conditions**
    - Capture **image sequences**
- ⇒ Denoising as initial preprocessing



## Denoising Methods – Overview

- Single-frame denoising: e. g. edge preserving filtering per frame
- Multi-frame denoising: single denoised image from noisy image sequence
  - (Adaptive) frame averaging
  - More robust estimators: temporal median, temporal RANSAC
  - Wavelet multi-frame<sup>1</sup>

**Our method:** adaptive and incremental averaging

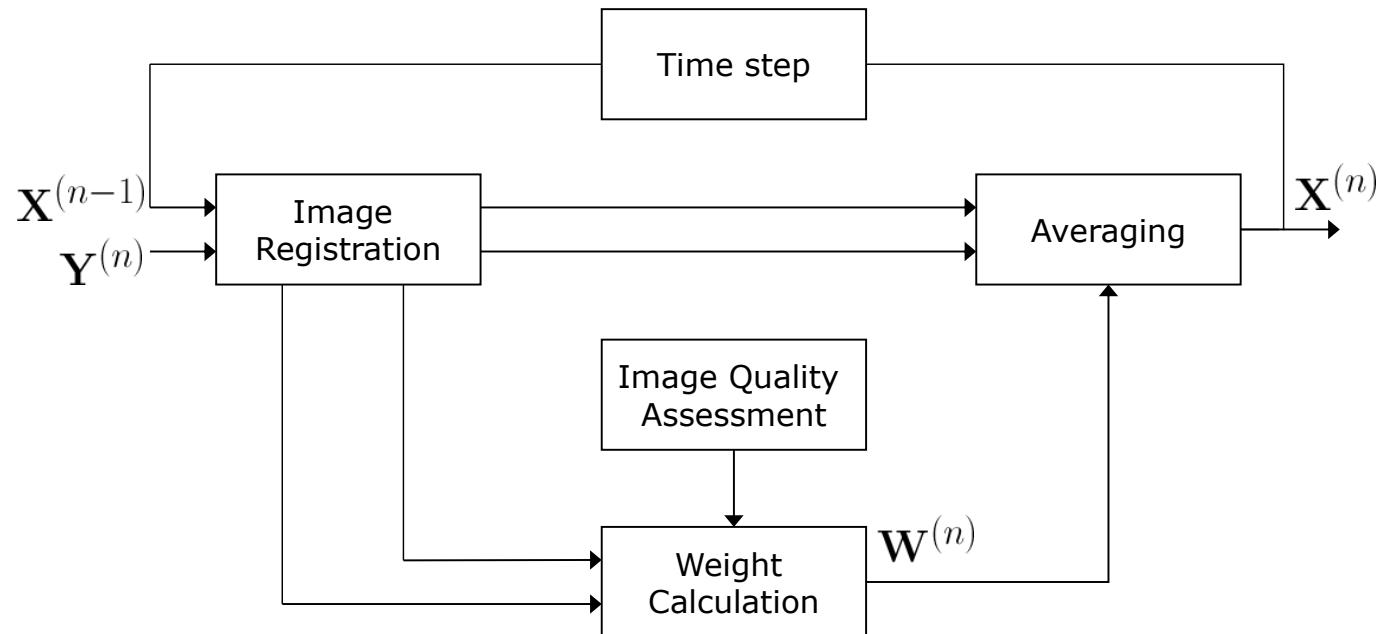
- Average of captured frames  $\Rightarrow$  runtime efficient
- Incremental scheme  $\Rightarrow$  memory efficient for real-time application
- Adaptive to image quality  $\Rightarrow$  weighting of input frames

<sup>1</sup>Mayer et al., Wavelet denoising of multiframe optical coherence tomography data, Biomedical Optics Express, 2012



# Quality Guided Denoising Method

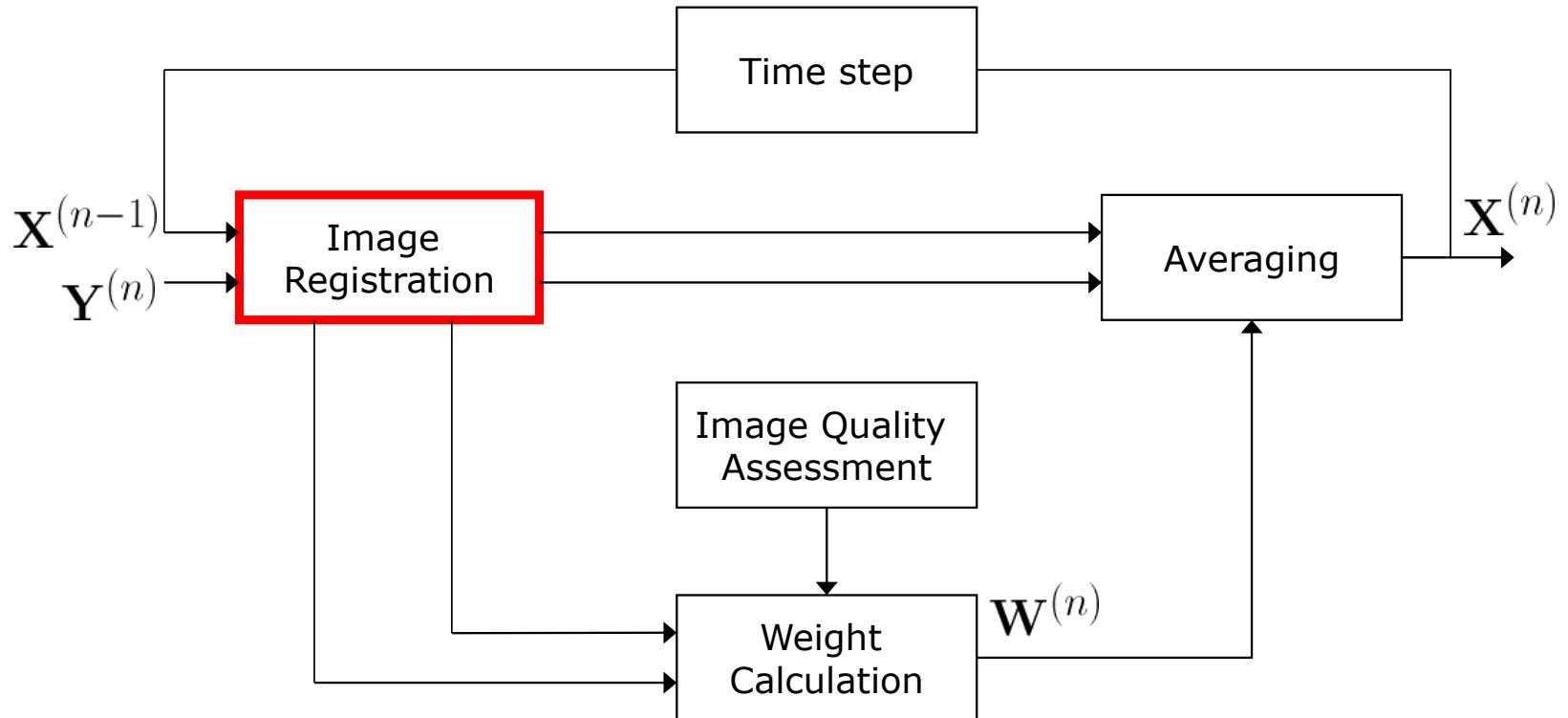
# Quality Guided Denoising – Algorithm Overview



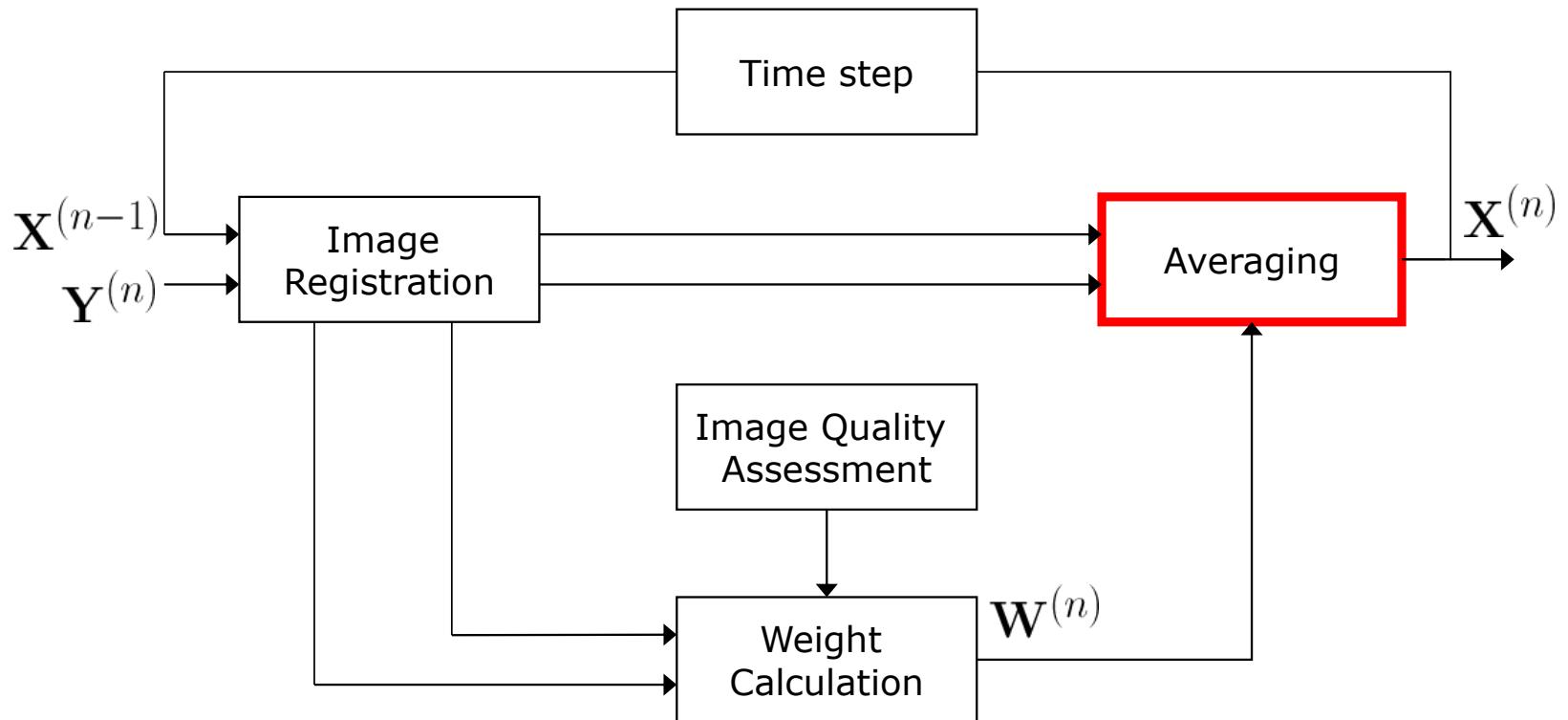
Incremental/recursive refinement:

- **Input:** Noisy frame  $\mathbf{Y}^{(n)}$  at time step  $n$
- **Output:** Denoised image  $\mathbf{X}^{(n)}$  based on  $\mathbf{Y}^{(n)}$  and previous  $\mathbf{X}^{(n-1)}$

# Image Registration



# Averaging



## Averaging

- Incremental scheme for frame averaging:

$$\mathbf{X}^{(n)} \equiv x_{ij}^{(n)} = \underbrace{w_{ij}^{(n)} x_{ij}^{(n-1)}}_{\text{previous estimation}} + \underbrace{\left(1 - w_{ij}^{(n)}\right) y_{ij}^{(n)}}_{\text{new input}}$$

$\mathbf{X}^{(n)}$ : Refined denoised image (based on  $n$  frames)

$\mathbf{X}^{(n-1)}$ : Previous estimation (based on  $n - 1$  frames)

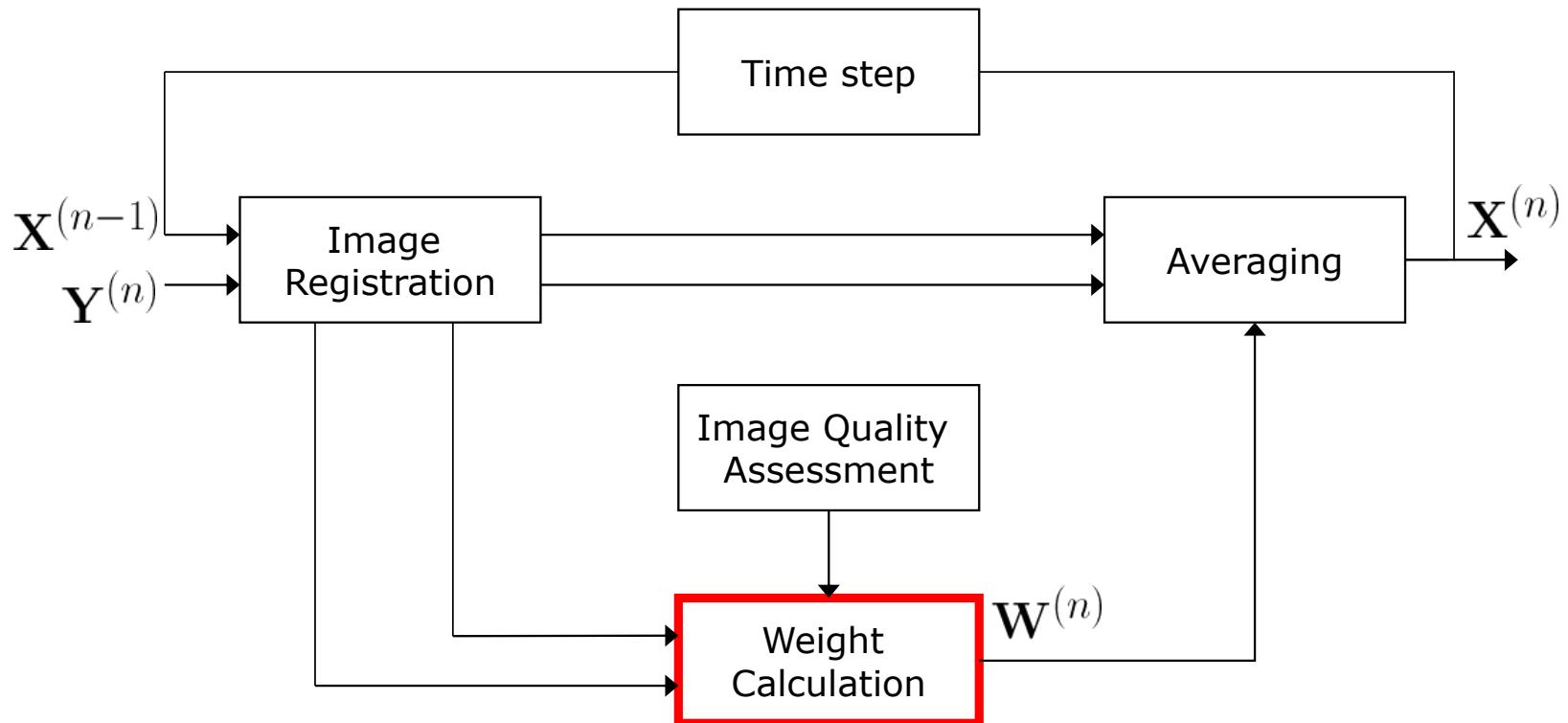
$\mathbf{Y}^{(n)}$ :  $n^{\text{th}}$  input image

$\mathbf{W}^{(n)}$ : Incremental weight matrix for  $\mathbf{X}^{(n-1)}$  and  $\mathbf{Y}^{(n)}$

**Goal:** Find optimal weights  $\mathbf{W}^{(n)} \equiv w_{ij}^{(n)}$  for denoising

- Update  $\mathbf{X}^{(n)}$  at each time step.

# Weight Calculation



## Weight Calculation

- Weight matrix  $\mathbf{W}^{(n)}$  (single weights  $w_{ij}^{(n)}$ ) is adaptive with respect to image content.
- Compose two types of weights:

$$w_{ij}^{(n)} = b_{ij}^{(n)} e_{ij}^{(n)}$$

$B^{(n)}$ : **Suppress outliers**

$E^{(n)}$ : **Edge weights** based on image quality assessment

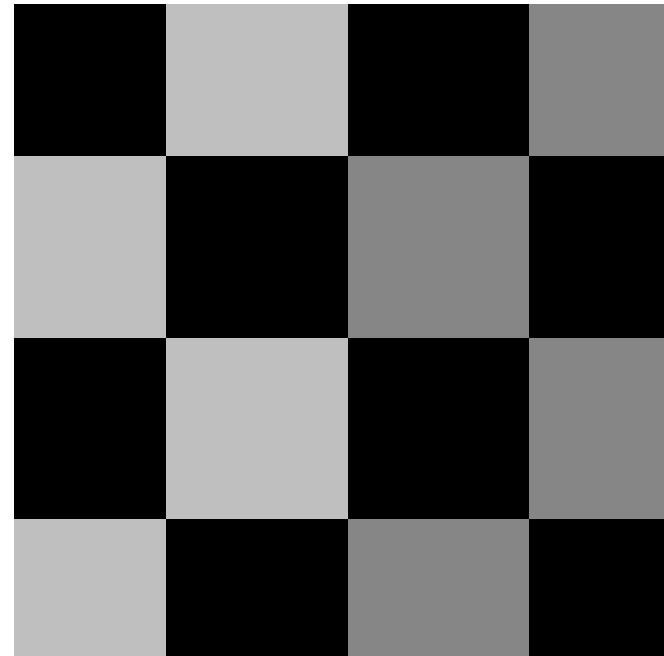
# Weight Calculation – Detect Outliers with $b_{ij}^{(n)}$

- Outliers caused by:
  - Inaccurate registration on edges (blur)
  - Salt-and-pepper or illumination artifacts in homogeneous regions
- Use temporal weights for outlier suppression:

$$b_{ij}^{(n)} = \frac{1}{1 + G_\sigma \left( x_{ij}^{(n-1)} - y_{ij}^{(n)} \right)}$$

$G_\sigma$ : Gaussian kernel

Reference image



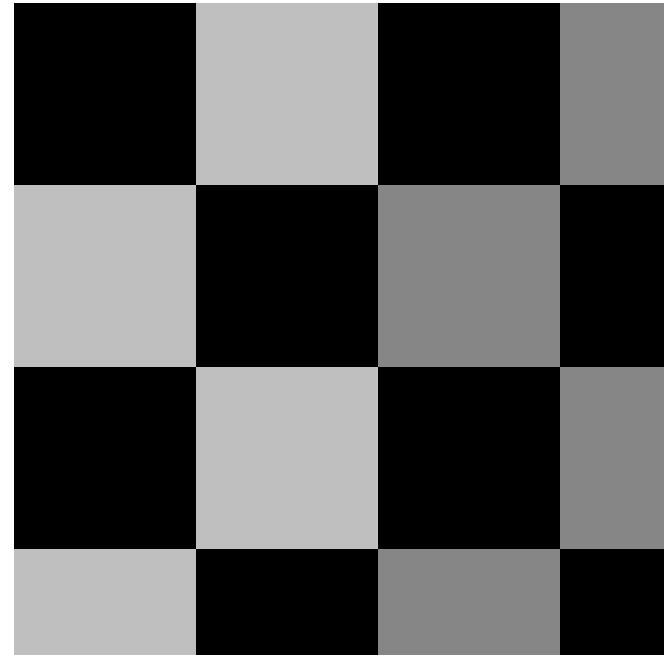
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Template image (mis-registered)



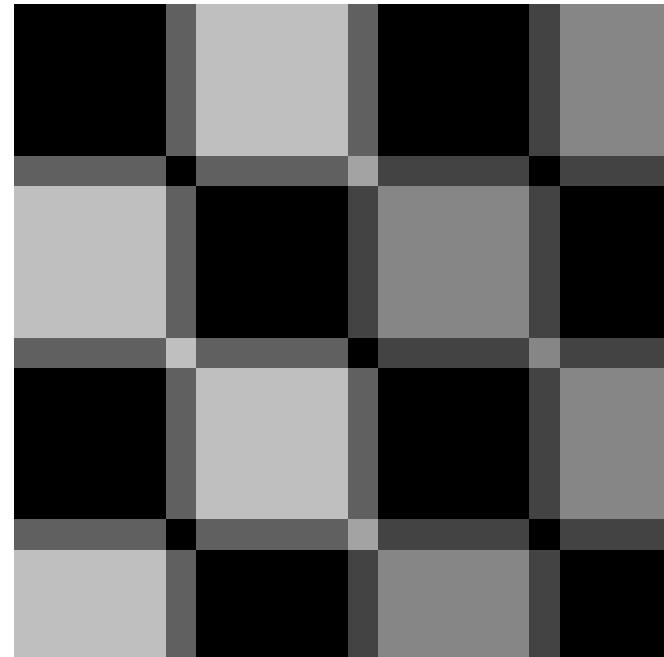
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Average image



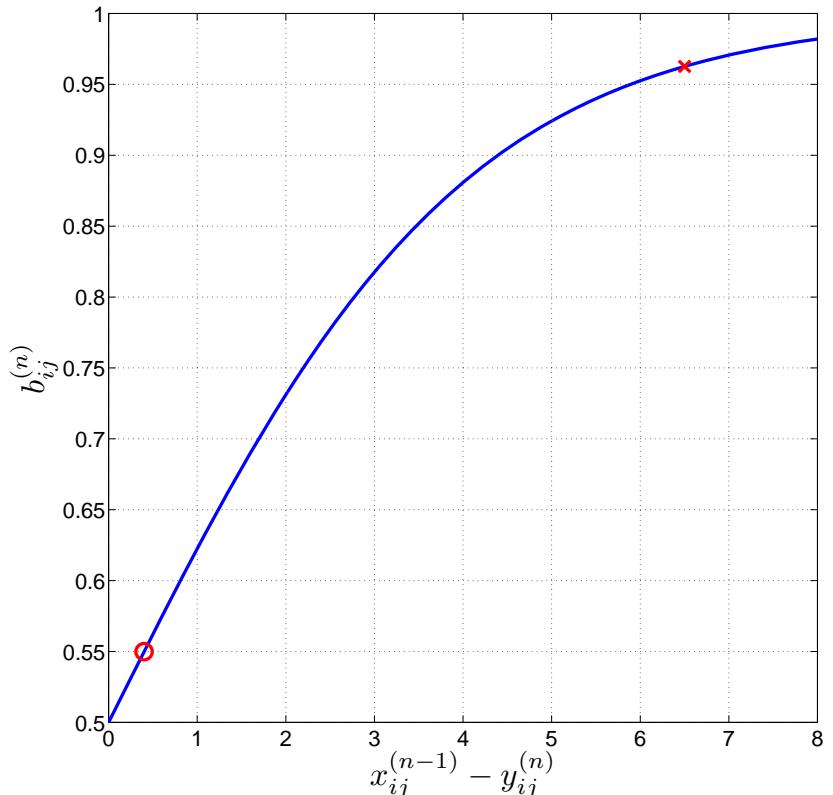
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Weights  $b_{ij}^{(n)}$



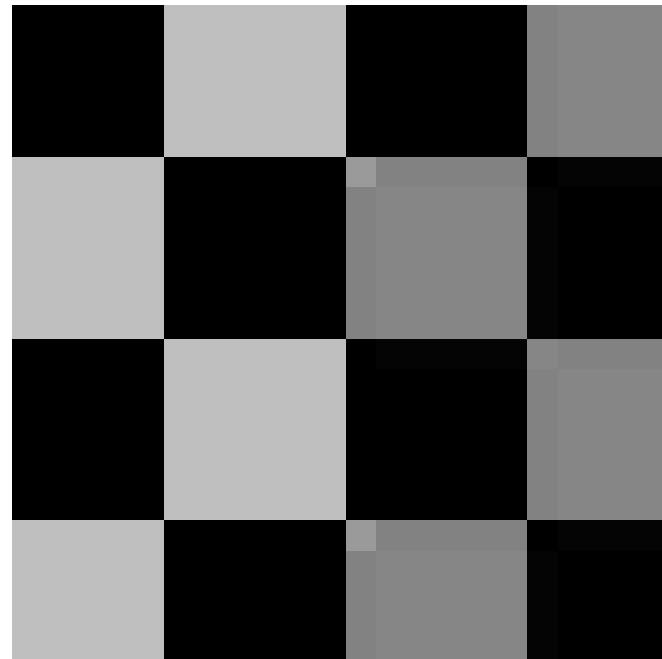
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$$b_{ij}^{(n)} = \frac{1}{1 + G_\sigma \left( x_{ij}^{(n-1)} - y_{ij}^{(n)} \right)}$$

$G_\sigma$ : Gaussian kernel

Average with  $b_{ij}^{(n)}$



## Weight Calculation – Edge Weights $e_{ij}^{(n)}$

- Decompose image into blocks
- Perform edge detection  $\Rightarrow$  edge strength  $\tau_{ij}$
- For each block: classify image points
  - Edge points  $\tau_{ij} > \tau_u$ : find weights that maximize **image quality index**  $Q(\cdot)$

$$e_{ij}^{(n)} = \alpha^* = \arg \max_{\alpha} Q(\alpha \mathbf{X}^{(n-1)} + (1 - \alpha) \mathbf{Y}^{(n)})$$

- Homogeneous points  $\tau_{ij} < \tau_l$ : simple averaging  $e_{ij}^{(n)} = \frac{n-1}{n}$
- Interpolate weights between homogeneous and strong edge points

$$e_{ij}^{(n)} = \begin{cases} \alpha^* & \text{if } \tau_{ij} > \tau_u \\ m\tau_{ij} + t & \text{if } \tau_l \leq \tau_{ij} \leq \tau_u \\ \frac{n-1}{n} & \text{if } \tau_{ij} < \tau_l \end{cases}$$

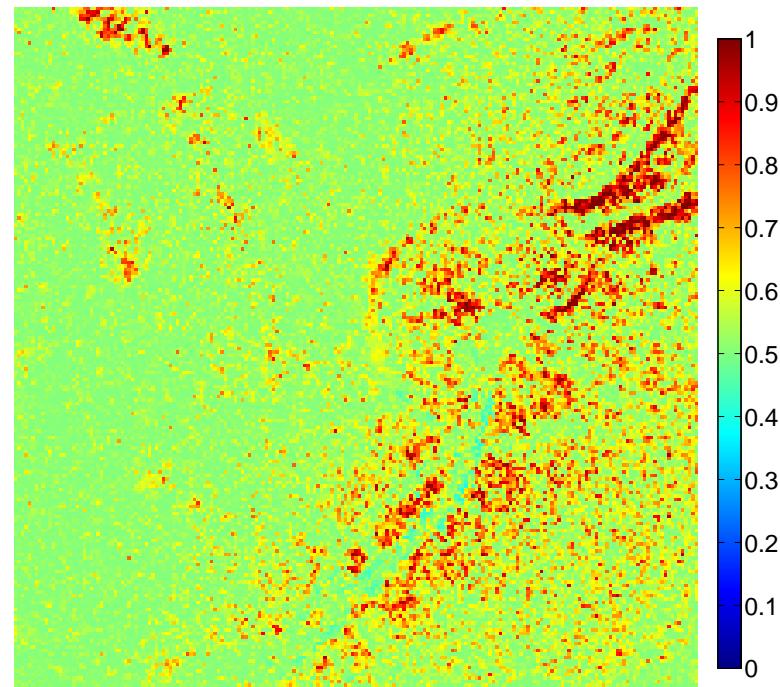
- Smooth over blocks to avoid boundary artifacts

## Weight Calculation – Composition to $W^{(n)}$

Compose single weights to weight matrix  $W^{(n)}$ :

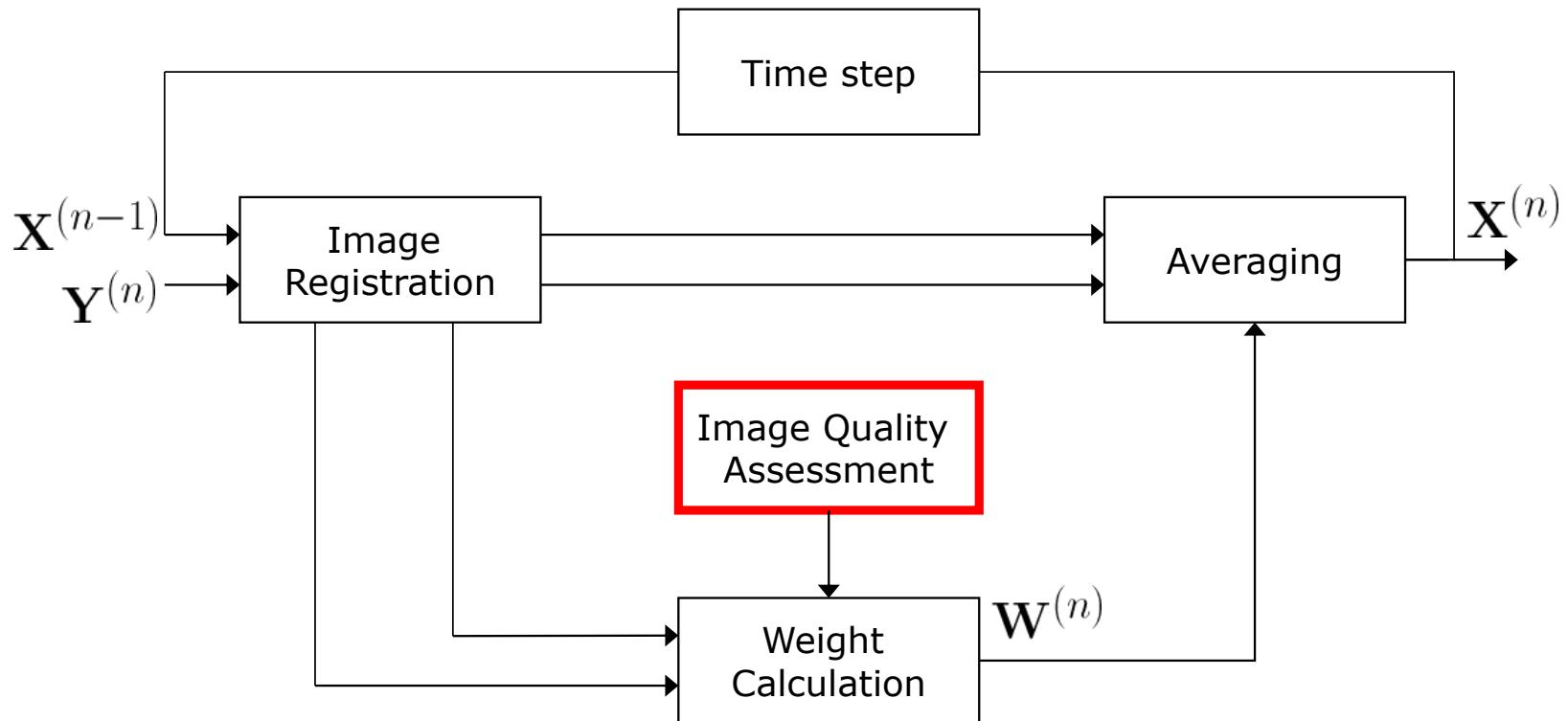


(a) Input fundus image



(b) Weight matrix  $W^{(n)}$

# Image Quality Assessment



# Image Quality Assessment

- Definition of image quality index  $Q(\cdot)$
- Different metrics can be used.
- Examples: measurement of blur, contrast, . . .
- Here: **edge magnitude distribution**<sup>2</sup>
  1. Calculate gradient magnitude image
  2. Determine histogram of gradient image
  3. Quality index: **skewness** of gradient histogram

Large Skewness  $\Rightarrow$  good separation between weak/strong edges  $\Rightarrow$  better subjective/objective quality

<sup>2</sup>Murillo et al., Proc. SPIE, Medical Imaging 2011: Image Processing, 2011

## Algorithm Properties – Run Time/Memory

Time/memory complexity in **incremental mode** vs. number of frames  $n$ :

Time complexity:

Method	Complexity
Median	$O(n)$
Wavelet	$O(n)$
<b>Quality guided</b>	$O(1)$

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Memory complexity:

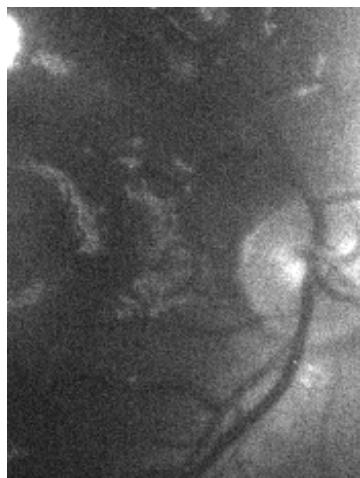
Method	Complexity
Median	$O(n)$
Wavelet	$O(n^2)$
<b>Quality guided</b>	$O(1)$



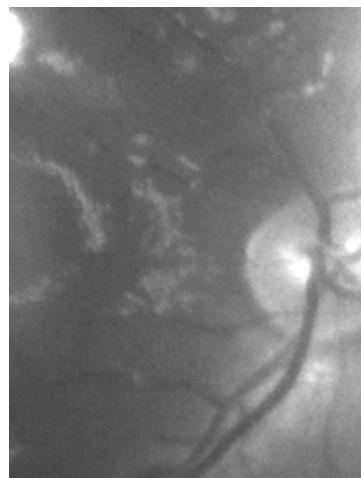
# Experiments and Results

## Qualitative Comparison

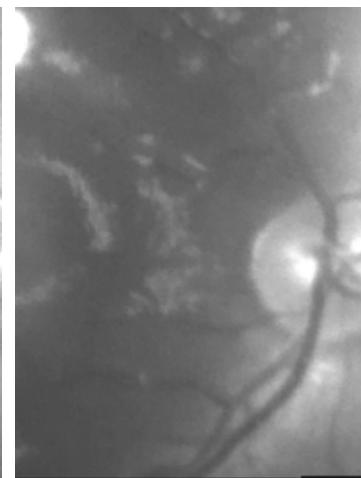
- Denoising based on 8 frames
- Comparison of
  - Temporal median
  - Wavelet multi-frame
  - Our method



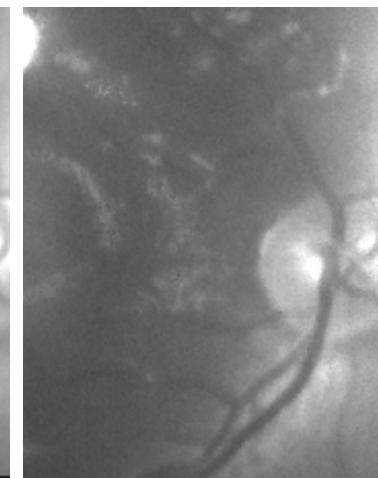
(c) Single frame



(d) Temporal median



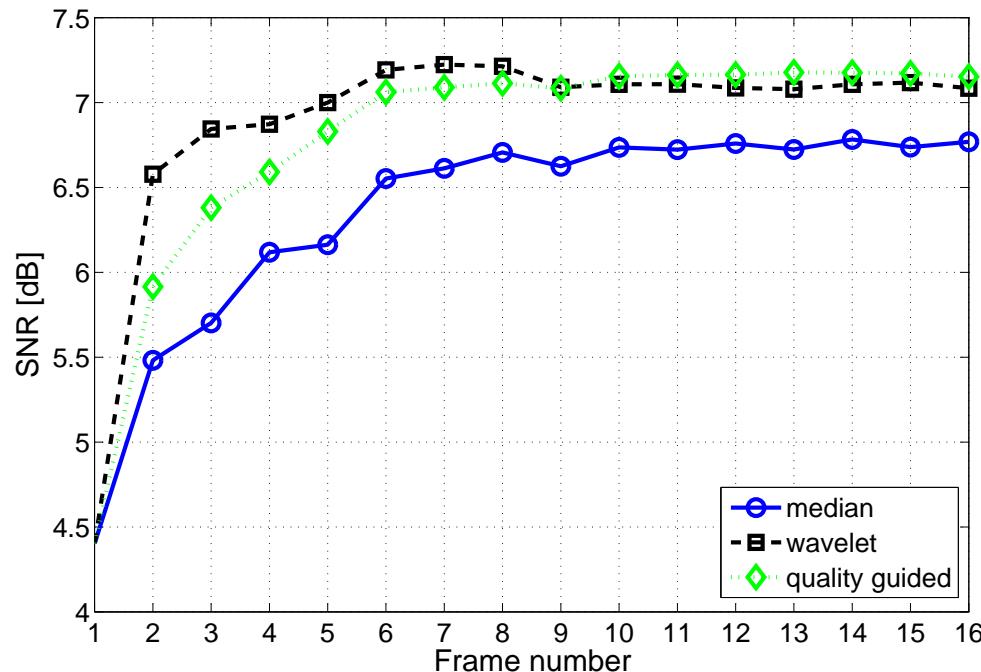
(e) Wavelet multi-frame



(f) Quality guided

# Denoising Performance

Evaluation of **signal-to-noise ratio (SNR)** for varying number of frames:



Quality guided denoising:

- Outperforms non-adaptive median method
- Short sequences ( $n < 5$ ): smaller SNR than wavelet multi-frame method
- Long sequences ( $n \geq 5$ ): competitive SNR



# Summary and Conclusion

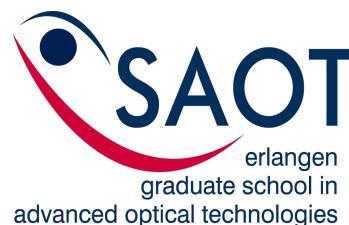
## Summary and Conclusion

- Multi-frame denoising with application to low-cost fundus imaging
- Adaptive and incremental frame averaging
  - Takes objective image quality index into account
  - Using adaptive weighting scheme based on image quality and temporal weights
  - Competitive SNR to state-of-the-art methods
  - But: efficient implementation (run time and memory)

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