



Multi-Frame Super-Resolution with Quality **Self-Assessment for Retinal Fundus Videos**

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Background

Fundus video cameras enable the **non-invasive acquisition** of fast temporal changes on the human retina. The low spatial resolution limits their diagnostic applicability.

Contribution: Reconstruction of high-resolution retinal fundus images from low-resolution, low-cost video data by means of multi-frame super-resolution to enhance diagnostic usability.

Experiments and Results

- 1. Experiments for synthetic fundus images:
 - Ground truth images taken from the DRIVE database
 - Simulation: random translations for eye motion, blurring by a Gaussian PSF, subsampling and Gaussian noise

• Super-resolution: K = 16 frames for $2 \times$ magnification Evaluation of the peak-signal-to-noise ratio (PSNR) and influence of super-resolution to blood vessel segmentation:

Problem Statement

Generative image model: Each frame $y^{(k)}$ for $k = 1, \ldots, K$ is a low-resolution observation of the high-resolution image x:

$$\boldsymbol{y}^{(k)} = \boldsymbol{\gamma}_m^{(k)} \odot \boldsymbol{D} \boldsymbol{B}^{(k)} \boldsymbol{M}^{(k)} \boldsymbol{x} + \boldsymbol{\gamma}_a^{(k)} \boldsymbol{1} + \boldsymbol{\epsilon}^{(k)}$$
$$= \boldsymbol{\gamma}_m^{(k)} \odot \boldsymbol{W}^{(k)} \boldsymbol{x} + \boldsymbol{\gamma}_a^{(k)} \boldsymbol{1} + \boldsymbol{\epsilon}^{(k)}$$

- Eye motion modeled by geometric transformation $M^{(k)}$
- Point spread function (PSF) $B^{(k)}$, subsampling D, noise $\epsilon^{(k)}$
- Inhomogeneous illumination modeled by $\gamma_m^{(k)}$ and $\gamma_a^{(k)}$

Objective: Given a sequence of K low-resolution frames $y^{(1)}, \ldots, y^{(K)}$, reconstruct unknown high-resolution image x

Proposed Super-Resolution Framework



	LR frame	SR image	Ground truth
PSNR (in dB)	31.09 ± 3.10	$\textbf{31.92} \pm \textbf{3.39}$	-
Sensitivity (%) Specificity (%)	$57.59 \pm 6.01 \\ 94.31 \pm 1.40$	$\begin{array}{r} \textbf{70.37} \pm \textbf{5.00} \\ \textbf{93.99} \pm \textbf{1.26} \end{array}$	$\begin{array}{c} 72.85 \pm 6.70 \\ 94.57 \pm 1.34 \end{array}$

Peak-signal-to-noise ratio (PSNR) for synthetic images generated from the Figure 2: DRIVE database as well as sensitivity and specificity for automatic vessel segmentation.

Super-resolution enhanced mean PSNR by 0.8 dB and sensitivity for automatic vessel segmentation by 13%

2. Experiments for low-cost fundus video camera:

- Videos of 6 healthy subjects (\approx 15 s video per subject)
- System parameters: CCD camera ($640 \times 480 \, \text{px}$), 20° field of view (FOV), 12.5 Hz frame rate
- Super-resolution: K = 8 frames for $2 \times$ magnification

Comparison of super-resolved video data to high-resolution Kowa NonMyd images ($1600 \times 1216 \, \text{px}, 25^{\circ} \, \text{FOV}$):

Figure 1: Flowchart of the proposed multi-frame super-resolution framework.

- 1. Photometric and geometric registration for each lowresolution frame k = 2, ..., K using k = 1 as reference:
 - Estimate photometric parameter $\gamma_m^{(k)}$ using B-spline approximation [1] of the bias field and $\gamma_a^{(k)}$ by the median temporal brightness difference
 - Small, natural eye motion is modeled by $M^{(k)}$ and subpixel motion is estimated by affine registration [2]
- 2. Super-resolution image reconstruction:

$$\hat{\boldsymbol{x}} = \arg\min_{\boldsymbol{x}} \left\{ \sum_{k=1}^{K} \left\| \boldsymbol{y}^{(k)} - \boldsymbol{\gamma}_{m}^{(k)} \odot \boldsymbol{W}^{(k)} \boldsymbol{x} - \boldsymbol{\gamma}_{a}^{(k)} \boldsymbol{1} \right\|_{1} + \lambda R(\boldsymbol{x}) \right\}$$

 $R(\boldsymbol{x})$ is an edge preserving regularizer weighted by λ



(a) Original (low-resolution) frame

(c) Kowa NonMyd image

Figure 3: Low-resolution and super-resolved image (magnification factor: 2) of the optic nerve head in comparison to a high-resolution image acquired with a Kowa NonMyd camera (images contrast enhanced for visual comparison).

 Q_v measure improved by 160 % w.r.t. to low-resolution data (compared to 86% for temporal median filtering)

Conclusion

Novel super-resolution framework for fundus video imaging:

• Geometric and photometric registration to model eye

 \rightarrow Iterative scaled conjugate gradient (SCG) optimization

3. Image quality self-assessment:

• Quality metric $Q_v(\boldsymbol{x})$ for anisotropic patches $\boldsymbol{p}_i \in \mathcal{P}(\boldsymbol{x})$:

 $Q_v(\boldsymbol{x}) = \sum_{\boldsymbol{p}_i \in \mathcal{P}(\boldsymbol{x})} \sigma_i \cdot q(\boldsymbol{p}_i)$

Local quality score $q(\mathbf{p}_i)$ adaptively weighted by local variance σ_i estimated from of the vesselness in p_i [3]

• Automatic selection of regularization weight λ :

 $\hat{\lambda} = \arg\max_{\lambda} Q_v(\boldsymbol{x}_{\lambda})$

 \boldsymbol{x}_{λ} : super-resolved image reconstructed with weight λ \rightarrow Joint super-resolution and parameter selection

motion and inhomogeneous illumination

- Image quality self-assessment for automatic selection of regularization parameter
- Quality of super-resolved low-cost images comparable to a high-resolution Kowa NonMyd camera

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