3-D OCT Motion Correction Efficiently Enhanced with OCT Angiography

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Motivation



Distortion between B-scans







Aims of Motion Correction

- Arbitrary slicing
- Accurate & reproducible disease metrics
- Directly compare with follow-up scans
- Prevent gaps from blinks and saccades

not corrected motion corrected





Registration-based Motion Correction

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Scan Alignment vs. Motion Correction

| | Alignment | Motion Correction |
|---------------------|---|--------------------------|
| Align scans | \checkmark | |
| SNR improvement | A 10 and 10 a | |
| Correct distortions | * | |



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Quantitative 3D-OCT motion correction with tilt and illumination correction, robust similarity measure and regularization

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Abstract: Variability in illumination, signal quality, tilt and the amount of motion pose challenges for post-processing based 3D-OCT motion







Key properties:

Orthogonal scan based







Key properties:

- Orthogonal scan based
- Full 3-D per A-scan displacement field

A-scan center
3-D displacement
(One displacement field *per volume*.)







- V_i: OCT volumes
- D: displacement field

Key properties:

- Orthogonal scan based
- Full 3-D per A-scan displacement field
- Gradient-based optimizer (L-BFGS)







Key properties:

- Orthogonal scan based
- Full 3-D per A-scan displacement field
- Gradient-based optimizer
- Physiologically reasonable displacements (*R*)





Why add angiography data?

OCT data

High axial contrast



Low contrast in transverse dir.





High contrast in transverse dirs.





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Efficient Use of Angiography Data



- OCTA adds little information along depth
- Use 2-D en-face OCTA projections





Fast Computation of OCTA Projections

Layer segmentation based



- Best quality
- Slow to compute

Our approach



- Fast to compute
- Not as nice, but sufficient





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Fast Computation of OCTA Projections







Fast Computation of OCTA Projections







Corrupted OCTA Data





OCTA validity

• Fall back to OCT only for saccadic B-scans

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En-face OCTA

$$\min_{D} (1 - \mathbf{A}) \cdot \mathbf{D}(V_1, V_2, D) + \mathbf{A} \cdot \mathbf{D}(A_1, A_2, D) + \alpha \cdot \mathbf{R}(D)$$

OCT term OCTA term





Evaluation





Qualitative Evaluation, OCT Data Only





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Qualitative Evaluation, with OCTA Data









Qualitative Evaluation, with OCTA Data

| | OCT | OCTA | NIN I | | $X \mapsto$ | Star . |
|--------|-----|---|---|--|-------------|--------|
| Scan 1 | | In the fractions in the fraction of the fracti | n the evaluation tion of success increased from | n dataset, sful registrations n 75% to 93% | | S C |
| | | | # subjects | # registrations | # failed | 1 122 |
| Scan 2 | | Normal | 10 | 60 | 1 | |
| | | Pathological (*) | 7 | 42 | 6 | |
| | | Total | 17 | 102 | 7 | XX |
| | Ali | (*) NAION, Dry AN | /ID, AMD w/ G | A, DM no DR, PDF | R w/ DME | KS |

20





Quantitative Evaluation

• Metrics related to clinically relevant features



Depth position of ILM



Vessel maps





Alignment Performance







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Motion Correction Performance



- Independent corrections
 - same eye, different motion
- Motion corrected volumes agree (they are *reproducible*)





Vessel Map Difference over OCTA Weight

Alignment performance

Motion correction performance



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Vessel Map Difference over Regularization Weight

Alignment performance

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Motion correction performance



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25





Conclusions

- OCTA data can improve
 - reliability and
 - accuracy of motion correction.
- En-face OCTA is sufficient and can be computed quickly.
- Motion correction evaluation reveals that the anisotropic nature of OCT scanning should be modeled.





Collaborators

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 - Eric Moult

- Ben Potsaid
- Patrick Yiu
- New England Eye Center

- Yasin Alibhai
- Caroline Baumal
- Jay Duker
- Eduardo Novais
- Carl Rebhun
- Nadia Waheed

Thank you for your attention.













30

ILM depth over regularization weight

Registration Performance

20 20 OCT only Mean Error (μm) 5 01 21 Error (μ m) ✓with OCTA 15 10 Mean 5 0 $\left(\right)$ 0.001 0.01 0 0.001 0.1 0.01 0.1 0 α_{0} α_0 Digital resolution: 4.5 μm , segmentation pixel accurate only -> we cannot reach $0\mu m$ Stefan B. Ploner | Pattern Recognition Lab, FAU Erlangen | 3-D OCT Motion Correction Efficiently Enhanced with OCTA 05/02/2018

Reproducibility Performance





Hardware vs. Software Motion Correction

Hardware

- Operates on lower frequency / lower resolution surrogate signal
- Drastically reduces gap size, small gaps may remain due to limited accuracy
- Single scan suffices

Software

- Operates on full OCT resolution
- Small gaps can remain if they were not scanned in any scan
- Delay due to computation time
- SNR improvement through averaging
- Device independent
- Can be applied & optimized
 retrospectively if all scans were stored

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Combine both for best reliability & accuracy.





Parallel scans

- No reference along slow scan axis, displacements can at best be averaged
- Trivial application to widefield scans
- Gap overlap unlikely
- If gaps remain, whole slices are missing, extent unknown

Orthogonal scans

- Fast scans along both axes allow for accurate motion correction
- Non-trivial application to widefield scans
- When using two scans, gaps from different scans always have a known, small overlap







- Unknown extent in fast scan dir.
 A third a due to missing reference
 advanta
- A third scan combines the advantages

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