# Convex Optimization of the Sammon Transformation

Thesis Introduction

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### Convex Optimization of the Sammon Transformation

- The Sammon Transformation
- Test data sets
- Lagrange Multipliers
- Following steps



# **The Sammon Transformation**



#### **Sammon Transformation**

- In 1969 John Sammon published an article about a non linear mapping for data structure analysis
- It is a mapping from a high-dimensional space to a lower-dimensional space
- The inner point distances of the points are preserved as good as possible over the transformation
- The Stress Function is an indicator for how big the difference of the inner point distances in the different spaces is
- For finding the best fitting points in the low dimensional space we have to minimize this equation.



#### **Sammon Stress Function:**

$$E = \frac{1}{\sum_{i < j} d_{ij}} \sum_{i < j}^{N} \frac{(d_{ij} - || \boldsymbol{x}_i - \boldsymbol{x}_j ||_2)^2}{d_{ij}}$$

 $d_{ij}$  are the inner point distances in the original space.  $\mathbf{x}_i, \mathbf{x}_i$  are the projected points in the low-dimensional space.



# **Properties of the Sammon Mapping**



# **Properties of the Sammon Mapping**

• Preserves the grouping of the points



## **Properties of the Sammon Mapping**

- Preserves the grouping of the points
- Preserves the overall structure of the points

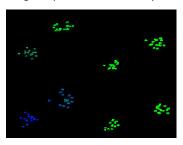


# Test data sets

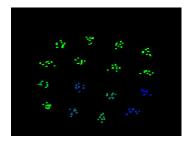


# **Hypercube**

#### Original points in the 3D-space



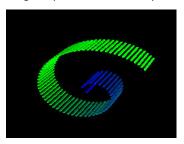
#### A good solution would be:



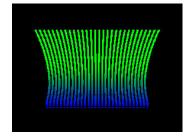


#### **Swiss Roll**

Original points in the 3D-space



A good solution would be:





# **Lagrange Multipliers**



#### **Definition**

$$\begin{array}{ll} \text{minimize} & \textit{f}_0(\textbf{\textit{x}}) \\ \text{subject to} & \textit{f}_i(\textbf{\textit{x}}) \leq 0 \;, \quad i=1,...,m; \\ & \textit{h}_i(\textbf{\textit{x}}) = 0 \;, \quad i=1,...,p; \end{array}$$



#### **Definition**

minimize 
$$f_0(\mathbf{x})$$
  
subject to  $f_i(\mathbf{x}) \leq 0$ ,  $i = 1, ..., m$ ;  
 $h_i(\mathbf{x}) = 0$ ,  $i = 1, ..., p$ ;

The Lagrangian is defined as:

$$L(\boldsymbol{x}, \boldsymbol{\lambda}, \boldsymbol{\nu}) = f_0(\boldsymbol{x}) + \sum_{i=1}^m \lambda_i f_i(\boldsymbol{x}) + \sum_{i=1}^p \nu_i h_i(\boldsymbol{x})$$



## **Lagrangians of the Sammon Transformation**

• Linear constraint:  $d_{ii} = ||\boldsymbol{x}_i - \boldsymbol{x}_i||_2 \ \forall i, j$ 

$$L(\boldsymbol{x}, \boldsymbol{
u}) = \sum_{i,j} 
u_{ij}(||\boldsymbol{x}_i - \boldsymbol{x}_j||_2 - d_{ij})$$



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• Quadratic constraint:  $d_{ij}^2 = ||\boldsymbol{x}_i - \boldsymbol{x}_j||_2^2 \ \forall i, j$ 

$$L(\boldsymbol{x}, \boldsymbol{\nu}) = \sum_{i,i} \nu_{ij} (d_{ij}^2 - ||\boldsymbol{x}_i - \boldsymbol{x}_j||_2^2)$$



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$$L(\boldsymbol{x}, \boldsymbol{\nu}) = \sum_{i,j} \nu_{ij} (d_{ij}^2 - ||\boldsymbol{x}_i - \boldsymbol{x}_j||_2^2)$$

Based on these Lagrangians, we found different objective functions, in which we can chose different weighting factors. For example for a stronger weighting of small distances.



# Following steps





• Comparison of the different objective functions



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- Finding the best possible weighting factors



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- Looking for a faster method to find the global minimum than a gradient descent



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#### Aim of the thesis:

Finding a convex function with the same properties like the Sammon Transformation which also minimizes the Stress Function.

