

# Constructing and implementing orthogonal and biorthogonal wavelet transforms via liftings

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- *Lifting* is a particular method for constructing and implementing orthogonal and biorthogonal (pairs of) filters and discrete wavelet transforms
- *Lifting* has close relations to classical topics in computer algebra: polynomial arithmetic and Euclid's algorithm in particular

- Haar WT uses the filters

$$\text{low-pass} \quad \mathbf{h} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \end{bmatrix}$$

$$\text{high-pass} \quad \mathbf{g} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \end{bmatrix}$$

- orthogonal matrix

$$H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}.$$

- operation on signals

$$\mathbf{a} = (a_n)_{n \in \mathbb{Z}} \mapsto \begin{cases} \tilde{\mathbf{a}} = (\tilde{a}_n)_{n \in \mathbb{Z}} \\ \tilde{\mathbf{d}} = (\tilde{d}_n)_{n \in \mathbb{Z}} \end{cases}$$

where

$$\tilde{a}_n = \frac{1}{\sqrt{2}} (a_{2n} + a_{2n+1}), \quad \tilde{d}_n = \frac{1}{\sqrt{2}} (a_{2n} - a_{2n+1}).$$

- Using the technique of  $z$ -transforms (alias power series), one gets by separating the sequences of even- and odd-indexed coefficients

$$(\dots, a_{-2}, a_{-1}, a_0, a_1, a_2, a_3, \dots) \longleftrightarrow \begin{cases} (\dots, a_{-2}, a_0, a_2, \dots) \\ (\dots, a_{-1}, a_1, a_3, \dots) \end{cases}$$

the decomposition

$$a(z) = \sum_{n \in \mathbb{Z}} a_n z^n = a_{\text{even}}(z^2) + z \cdot a_{\text{odd}}(z^2),$$

where

$$a_{\text{even}}(z) = \sum_{n \in \mathbb{Z}} a_{2n} z^n = \left. \frac{a(z) + a(-z)}{2} \right|_{z^2 \leftarrow z},$$

$$a_{\text{odd}}(z) = \sum_{n \in \mathbb{Z}} a_{2n+1} z^n = \left. \frac{a(z) - a(-z)}{2z} \right|_{z^2 \leftarrow z}.$$

- The series for approximation and for detail are

$$\tilde{a}(z) = \sum_{n \in \mathbb{Z}} \tilde{a}_n z^n = \frac{1}{\sqrt{2}} (a_{\text{even}}(z) + a_{\text{odd}}(z)),$$

$$\tilde{d}(z) = \sum_{n \in \mathbb{Z}} \tilde{d}_n z^n = \frac{1}{\sqrt{2}} (a_{\text{even}}(z) - a_{\text{odd}}(z)).$$

- Writing this in matrix form (with power series as coefficients)

$$\begin{bmatrix} \tilde{a}(z) \\ \tilde{d}(z) \end{bmatrix} = H \cdot \begin{bmatrix} a_{\text{even}}(z) \\ a_{\text{odd}}(z) \end{bmatrix}$$

- This simple case is not typical, however, because the matrix entries are constants. In general they will be polynomials (including terms with negative  $z$ -powers)

- Now consider the following decomposition of the  $H$ -matrix:

$$H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} \sqrt{2} & 0 \\ 0 & -\frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

- Only very simple ( $2 \times 2$ )-matrices occur as factors:

- the diagonal matrix  $\begin{bmatrix} \sqrt{2} & 0 \\ 0 & -\frac{1}{\sqrt{2}} \end{bmatrix}$
- the special upper triangular matrix  $\begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix}$
- the special lower triangular matrix  $\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$

- “special” means: entries in the main diagonal are 1

- The decomposition can be interpreted as a *straight-line program* for parallel execution of the approximation-detail transformation

$$(a_{2n}, a_{2n+1}) \mapsto (\tilde{a}_n, \tilde{d}_n) \quad (n \in \mathbb{Z})$$

$$x \leftarrow a_{2n}$$

$$y \leftarrow a_{2n+1}$$

$$y \leftarrow y - x$$

multiplication by  $\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$

$$x \leftarrow x + \frac{1}{2}y$$

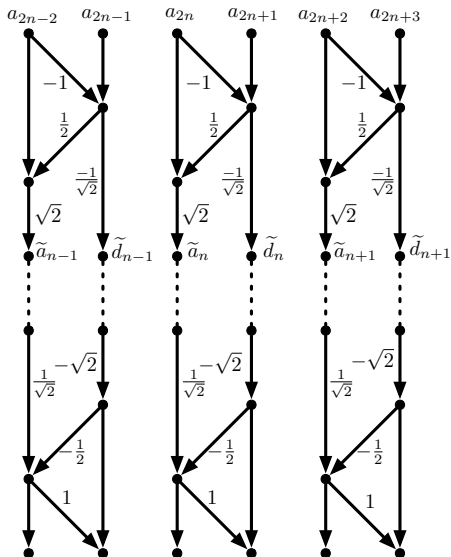
multiplication by  $\begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix}$

$$\begin{aligned} \tilde{a}_n &\leftarrow \sqrt{2}x \\ \tilde{d}_n &\leftarrow -\frac{1}{\sqrt{2}}y \end{aligned}$$

multiplication by  $\begin{bmatrix} \sqrt{2} & 0 \\ 0 & -\frac{1}{\sqrt{2}} \end{bmatrix}$



Graphical representation as a data flow diagram (including the inverse transformation)



- The decomposition of  $H$  immediately gives the decomposition of the matrix of the *inverse transformation*  $H^{-1}$

$$\begin{aligned} H^{-1} &= \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} \sqrt{2} & 0 \\ 0 & -\frac{1}{\sqrt{2}} \end{bmatrix}^{-1} \\ &= \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 \\ 0 & -\sqrt{2} \end{bmatrix} \end{aligned}$$

- Note: the diagonal and triangular matrices are easy to invert!
- The Haar situation is particular because  $H = H^{-1}$ , but the previous remark applies in general
- The decompositions of  $H$  and  $H^{-1}$  can be read as blueprints for implementation!

- Filter coefficients of the D4 transform

$$\begin{aligned}(h_0, h_1, h_2, h_3) &= \left( \frac{1 + \sqrt{3}}{4\sqrt{2}}, \frac{3 + \sqrt{3}}{4\sqrt{2}}, \frac{3 - \sqrt{3}}{4\sqrt{2}}, \frac{1 - \sqrt{3}}{4\sqrt{2}} \right) \\ &= (0.482963, 0.836516, 0.224144, -0.129410)\end{aligned}$$

$$\begin{aligned}(g_{-2}, g_{-1}, g_0, g_1) &= \left( \frac{-1 + \sqrt{3}}{4\sqrt{2}}, \frac{3 - \sqrt{3}}{4\sqrt{2}}, \frac{-3 - \sqrt{3}}{4\sqrt{2}}, \frac{1 + \sqrt{3}}{4\sqrt{2}} \right) \\ &= (0.129410, 0.224144, -0.836516, 0.482963)\end{aligned}$$

- polyphase matrix

$$\begin{bmatrix} h_{\text{even}}(z) & h_{\text{odd}}(z) \\ g_{\text{even}}(z) & g_{\text{odd}}(z) \end{bmatrix} = \begin{bmatrix} h_0 + h_2 z & h_1 + h_3 z \\ g_{-2} z^{-1} + g_0 & g_{-1} z^{-1} + g_1 \end{bmatrix}$$

- Decomposing the matrix of the D4 transform

$$\begin{bmatrix} h_{\text{even}}(z) & h_{\text{odd}}(z) \\ g_{\text{even}}(z) & g_{\text{odd}}(z) \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{3}-1}{\sqrt{2}} & 0 \\ 0 & \frac{\sqrt{3}+1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 1 & -z \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -\frac{\sqrt{3}}{4} & 1 \end{bmatrix} \begin{bmatrix} 1 & \sqrt{3} \\ 0 & 1 \end{bmatrix}$$

- define parameters

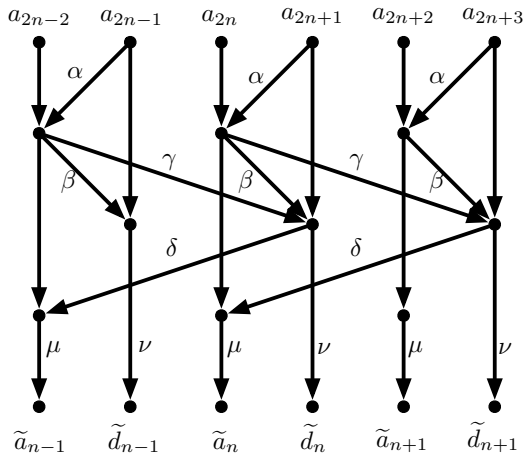
$$(\alpha, \beta, \gamma, \delta, \mu, \nu) = \left( \sqrt{3}, -\frac{\sqrt{3}}{4}, -\frac{\sqrt{3}-2}{4}, -1, \frac{\sqrt{3}-1}{\sqrt{2}}, \frac{\sqrt{3}+1}{\sqrt{2}} \right)$$

- D4 transform in terms of these parameters

$$\tilde{a}_n = \mu \left[ (1 + \gamma\delta)a_{2n} + (\alpha + \alpha\gamma\delta)a_{2n+1} \right. \\ \left. + \delta\beta a_{2n+2} + (\alpha\beta\delta + \delta)a_{2n+3} \right]$$

$$\tilde{d}_n = \nu \left[ (1 + \alpha\beta)a_{2n+1} + \beta a_{2n} + \alpha\gamma a_{2n-1} + \gamma a_{2n-2} \right]$$

- $D4$  analysis as data flow diagram



- $D4$  synthesis by inverting the decomposition

- General considerations

- $\downarrow$  = downsampling (factor 2)

$$\downarrow a(z) = a_{\text{even}}(z) = \left. \frac{a(z) + a(-z)}{2} \right|_{z^2 \leftarrow z}$$

$$a_{\text{odd}}(z) = \downarrow (z^{-1} \cdot a(z)) = \left. \frac{a(z) - a(-z)}{2z} \right|_{z^2 \leftarrow z}$$

- downsampling a convolution  $\mathbf{a} \star \mathbf{b}$  of two signals (or filters)

$$\begin{aligned} \downarrow (a(z) \cdot b(z)) &= \left. \frac{1}{2} (a(z)b(z) + a(-z)b(-z)) \right|_{z^2 \leftarrow z} \\ &= \frac{1}{2} \left( (a_{\text{even}}(z^2) + z a_{\text{odd}}(z^2))(b_{\text{even}}(z^2) + z b_{\text{odd}}(z^2)) \right. \\ &\quad \left. + (a_{\text{even}}(z^2) - z a_{\text{odd}}(z^2))(b_{\text{even}}(z^2) - z b_{\text{odd}}(z^2)) \right) \Big|_{z^2 \leftarrow z} \\ &= a_{\text{even}}(z) \cdot b_{\text{even}}(z) + z \cdot a_{\text{odd}}(z) \cdot b_{\text{odd}}(z), \end{aligned}$$

- filter bank with filters  $\mathbf{h}, \mathbf{g}$  followed by downsampling (reversed filters denoted by  $\overline{\mathbf{h}}$  and  $\overline{\mathbf{g}}$ )

$$\mathbf{a} = (a_n)_{n \in \mathbb{Z}} \mapsto \begin{cases} \tilde{\mathbf{a}} = (\tilde{a}_n)_{n \in \mathbb{Z}} = a_{\text{even}}(z) \cdot \overline{\mathbf{h}}_{\text{even}}(z) + z \cdot a_{\text{odd}}(z) \cdot \overline{\mathbf{h}}_{\text{odd}}(z) \\ \tilde{\mathbf{d}} = (\tilde{d}_n)_{n \in \mathbb{Z}} = a_{\text{even}}(z) \cdot \overline{\mathbf{g}}_{\text{even}}(z) + z \cdot a_{\text{odd}}(z) \cdot \overline{\mathbf{g}}_{\text{odd}}(z) \end{cases}$$

- matrix version of this transform

$$\begin{bmatrix} a_{\text{even}}(z) \\ a_{\text{odd}}(z) \end{bmatrix} \mapsto \begin{bmatrix} \tilde{a}(z) \\ \tilde{d}(z) \end{bmatrix} = \begin{bmatrix} \overline{\mathbf{h}}_{\text{even}}(z) & z \cdot \overline{\mathbf{h}}_{\text{odd}}(z) \\ \overline{\mathbf{g}}_{\text{even}}(z) & z \cdot \overline{\mathbf{g}}_{\text{odd}}(z) \end{bmatrix} \begin{bmatrix} a_{\text{even}}(z) \\ a_{\text{odd}}(z) \end{bmatrix}$$

- Note that

$$\overline{h}_{\text{even}}(z) = h_{\text{even}}(z^{-1}), \quad z \cdot \overline{h}_{\text{odd}}(z) = h_{\text{odd}}(z^{-1})$$

- so that the matrix of this transform can be written as

$$P(z^{-1})^t = \begin{bmatrix} h_{\text{even}}(z^{-1}) & h_{\text{odd}}(z^{-1}) \\ g_{\text{even}}(z^{-1}) & g_{\text{odd}}(z^{-1}) \end{bmatrix}$$

- The matrix

$$P(z) = \begin{bmatrix} h_{\text{even}}(z) & g_{\text{even}}(z) \\ h_{\text{odd}}(z) & g_{\text{odd}}(z) \end{bmatrix}$$

is known as the *polyphase matrix* belonging to the pair  $(\mathbf{h}, \mathbf{g})$  of filters



- Orthogonality of a pair  $(\mathbf{h}, \mathbf{g})$  of filters can be characterized in terms of the polyphase matrix as follows:
  - A pair  $(\mathbf{h}, \mathbf{g})$  of filters is orthogonal if and only if

$$P(z^2)^{-1} = P(z^{-2})^t$$

- Proof: see the Lecture Notes

- Bi-Orthogonality of a pair of filters  $(\mathbf{h}, \tilde{\mathbf{h}})$  can also be cast in terms of the polyphase matrix:
  - A pair of filters  $(\mathbf{h}, \tilde{\mathbf{h}})$  (together with filters  $\mathbf{g}$  und  $\tilde{\mathbf{g}}$  constructed as usual) is a biorthogonal pair if and only if

$$\tilde{P}(z^2)^{-1} = P(z^{-2})^t$$

- Proof: see the Lecture Notes

- What does “lifting” mean?

- The goal is to write the polyphase matrix  $P(z)$  of a filter pair  $(\mathbf{h}, \mathbf{g})$  as a product of very simple matrices

$$P(z) = \begin{bmatrix} h_{\text{even}}(z) & g_{\text{even}}(z) \\ h_{\text{odd}}(z) & g_{\text{odd}}(z) \end{bmatrix} = \begin{bmatrix} 1 & q_1(z) \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ q_2(z) & 1 \end{bmatrix} \begin{bmatrix} 1 & q_3(z) \\ 0 & 1 \end{bmatrix} \cdots \begin{bmatrix} 1 & 0 \\ q_k(z) & 1 \end{bmatrix} \begin{bmatrix} K & 0 \\ 0 & 1/K \end{bmatrix}$$

- w.l.o.g. assume that  $k$  is even
- The  $q_i(z)$  are power series  $\sum_{j \in \mathbb{Z}} q_j z^j$  with positive and possibly also with negative  $z$ -exponents
- If  $\mathbf{h}$  and  $\mathbf{g}$  are finite filters (the only case of interest for us) then the  $q_i(z)$  are polynomials in  $z$  in an extended sense:  
 $\sum_{j=s}^t q_j z^j$  with positive or negative bounds of summation  $s \leq t$   
 Generalized polynomials of this type are often called *Laurent-polynomials* (LP)

- Graphical representation of the analysis part of a filter bank using the product decomposition with coefficient polynomials  $q_j(z)$  of the polyphase matrix  $P(z)$

$$P(z) = \begin{bmatrix} h_{\text{even}}(z) & g_{\text{even}}(z) \\ h_{\text{odd}}(z) & g_{\text{odd}}(z) \end{bmatrix} = \begin{bmatrix} 1 & q_1(z) \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ q_2(z) & 1 \end{bmatrix} \begin{bmatrix} 1 & q_3(z) \\ 0 & 1 \end{bmatrix} \dots \begin{bmatrix} 1 & 0 \\ q_k(z) & 1 \end{bmatrix} \begin{bmatrix} K & 0 \\ 0 & 1/K \end{bmatrix}$$

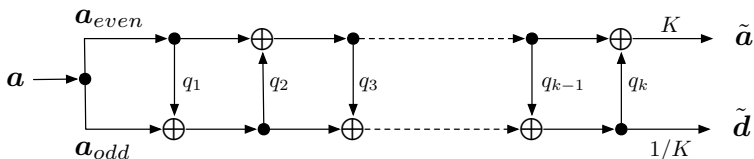


Figure: Lifting analysis

- Graphical representation of the synthesis part of a filter bank using the polynomials  $q_j(z)$  and the decomposition of the inverse of the polyphase matrix  $P(z)$

$$P(z)^{-1} =$$

$$\begin{bmatrix} 1/K & 0 \\ 0 & K \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -q_k(z) & 1 \end{bmatrix} \cdots \begin{bmatrix} 1 & -q_3(z) \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -q_2(z) & 1 \end{bmatrix} \begin{bmatrix} 1 & -q_1(z) \\ 0 & 1 \end{bmatrix}$$

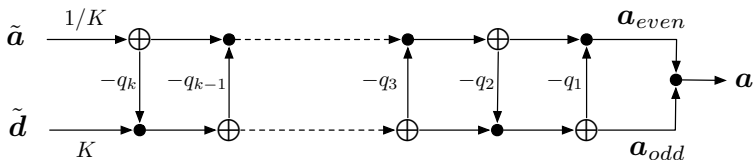


Figure: Lifting synthesis

- How to obtain the lifting decomposition of a polyphase matrix?

$$P(z) = \begin{bmatrix} h_{\text{even}}(z) & g_{\text{even}}(z) \\ h_{\text{odd}}(z) & g_{\text{odd}}(z) \end{bmatrix} = \begin{bmatrix} 1 & q_1(z) \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ q_2(z) & 1 \end{bmatrix} \begin{bmatrix} 1 & q_3(z) \\ 0 & 1 \end{bmatrix} \cdots \begin{bmatrix} 1 & 0 \\ q_k(z) & 1 \end{bmatrix} \begin{bmatrix} K & 0 \\ 0 & 1/K \end{bmatrix}$$

- Euclid's algorithm can be used for that!

- Consider polynomials (in the usual sense) with real or complex coefficients
- Fundamental property (division with remainder):
  - For any polynomials  $a(X)$ ,  $b(X)$  with  $b(X) \neq 0$  there exist (unique!) polynomials  $q(X)$  (the *quotient*) and  $r(X)$  (the *remainder*) s.th.

$$a(X) = b(X) \cdot q(X) + r(X),$$

where  $r(X) = 0$  or  $\deg r(X) < \deg b(X)$

- In perfect analogy to the situation with integers:  
iterated division with remainder can be used to compute the greatest common divisor (gcd) of two polynomials

- Scheme of Euclid's algorithm

$$\text{input } r_0 = r_0(X) = a(X)$$

$$r_1 = r_1(X) = b(X)$$

$$r_0 = r_1 \cdot q_1 + r_2$$

$$r_1 = r_2 \cdot q_2 + r_3$$

$$r_2 = r_3 \cdot q_3 + r_4$$

$$\vdots$$

$$r_{k-2} = r_{k-1} \cdot q_{k-1} + r_k \quad (r_k \neq 0)$$

$$r_{k-1} = r_k \cdot q_k + 0$$

$$\text{output } r_k(X) = \text{ggT}(a(X), b(X))$$



- Scheme of Euclid's algorithm in matrix form

$$\begin{bmatrix} r_1 \\ r_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & -q_1 \end{bmatrix} \begin{bmatrix} r_0 \\ r_1 \end{bmatrix}$$

$$\begin{bmatrix} r_0 \\ r_1 \end{bmatrix} = \begin{bmatrix} q_1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$$

$$\begin{bmatrix} r_2 \\ r_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & -q_2 \end{bmatrix} \begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$$

$$\begin{bmatrix} r_1 \\ r_2 \end{bmatrix} = \begin{bmatrix} q_2 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$$

$$\vdots$$

$$\vdots$$

$$\begin{bmatrix} r_{k-1} \\ r_k \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & -q_{k-1} \end{bmatrix} \begin{bmatrix} r_{k-2} \\ r_{k-1} \end{bmatrix}$$

$$\begin{bmatrix} r_{k-2} \\ r_{k-1} \end{bmatrix} = \begin{bmatrix} q_{k-1} & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} r_{k-1} \\ r_k \end{bmatrix}$$

$$\begin{bmatrix} r_k \\ 0 \end{bmatrix} = \begin{bmatrix} q_k & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} r_{k-1} \\ r_k \end{bmatrix}$$

$$\begin{bmatrix} r_{k-1} \\ r_k \end{bmatrix} = \begin{bmatrix} q_k & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} r_k \\ 0 \end{bmatrix}$$

- Putting things together one gets

$$\begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} r_0 \\ r_1 \end{bmatrix} = \begin{bmatrix} q_1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} q_2 & 1 \\ 1 & 0 \end{bmatrix} \cdots \begin{bmatrix} q_{k-1} & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} q_k & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} r_k \\ 0 \end{bmatrix}$$

- An easy modification is necessary to rewrite this decomposition in the way which is needed for the decomposition of the polyphase matrix

$$\begin{bmatrix} q & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ q & 1 \end{bmatrix} = \begin{bmatrix} 1 & q \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- The lifting-version of Euclid's algorithm is

$$\begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 1 & q_1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ q_2 & 1 \end{bmatrix} \begin{bmatrix} 1 & q_3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ q_4 & 1 \end{bmatrix} \cdots \begin{bmatrix} r_k \\ 0 \end{bmatrix}$$

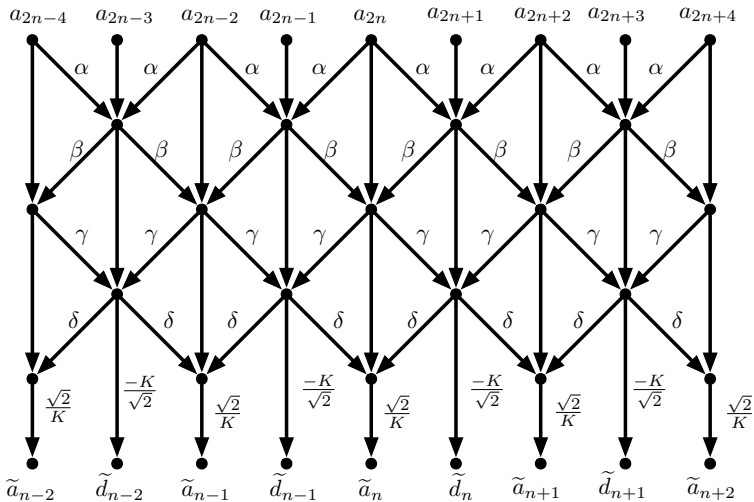
- Details how to employ Euclid's algorithm for the decomposition of the polyphase matrix will not be given here.
- The principle is important:
  - For a pair  $(\mathbf{h}, \mathbf{g})$  of orthogonal filters Euclid's algorithm applied the LPs  $h_{\text{even}}(z), h_{\text{odd}}(z)$  produces a lifting decomposition of the polyphase matrix

$$\begin{aligned}
 P(z) &= \begin{bmatrix} h_{\text{even}}(z) & g_{\text{even}}(z) \\ h_{\text{odd}}(z) & g_{\text{odd}}(z) \end{bmatrix} \\
 &= \begin{bmatrix} 1 & q_1(z) \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ q_2(z) & 1 \end{bmatrix} \cdots \begin{bmatrix} 1 & q_{k-1}(z) \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ q_k(z) & 1 \end{bmatrix} \begin{bmatrix} K & 0 \\ 0 & 1/K \end{bmatrix}
 \end{aligned}$$

- Polynomials  $g_{\text{even}}(z)$  and  $g_{\text{odd}}(z)$  are not used for computing this decomposition. The sequence of quotients  $q_1(z)$ ,  $q_2(z)$ ,  $\dots$  depends on  $h_{\text{even}}(z)$  and  $h_{\text{odd}}(z)$  only
- From the lifting decomposition and its quotient sequence one obtains automatically  $g_{\text{even}}(z)$  and  $g_{\text{odd}}(z)$

- The JPEG2000 standard for encoding, storing, compression and transmission of images employs two wavelet transforms:
  - The biorthogonal symmetric COHEN-DAUBECHIES-FEAUVEAU-(7,9) filter pair for *lossy* compression
  - the biorthogonal symmetric LEGALL-(5,3) filter pair for *lossless* compression

- Lifting scheme for the CDF-(9,7) wavelet



- Parameters for the biorthogonal CDF-(9,7) filter pair

$$\alpha = -1.586134342$$

$$\beta = -0.052980118$$

$$\gamma = 0.882911075$$

$$\delta = 0.443506852$$

$$K = 1.230174105$$

$$h_0 = \frac{\sqrt{2}}{K} [6\alpha\beta\gamma\delta + 2\alpha\beta + 2\gamma\delta + 2\alpha\delta + 1]$$

$$h_1 = \frac{\sqrt{2}}{K} [3\beta\gamma\delta + \beta + \delta]$$

$$h_2 = \frac{\sqrt{2}}{K} [4\alpha\beta\gamma\delta + \gamma\delta + \alpha\delta + \alpha\beta]$$

$$h_3 = \frac{\sqrt{2}}{K} [\beta\gamma\delta]$$

$$h_4 = \frac{\sqrt{2}}{K} [\alpha\beta\gamma\delta]$$

$$g_1 = \frac{-K}{\sqrt{2}} [1 + 2\beta\gamma]$$

$$g_2 = \frac{-K}{\sqrt{2}} [3\alpha\beta\gamma + \alpha + \gamma]$$

$$g_3 = \frac{-K}{\sqrt{2}} [\beta\gamma]$$

$$g_4 = \frac{-K}{\sqrt{2}} [\alpha\beta\gamma]$$

- The biorthogonal LEGALL-(5,3) filter pair
  - The filters are

$$\mathbf{h} = \frac{1}{8} [-1 \quad 2 \quad 6 \quad 2 \quad -1]_{-2..2}$$

$$\tilde{\mathbf{h}} = \frac{1}{2} [1 \quad 2 \quad 1]_{-1..1}$$

$$\mathbf{g} = \frac{1}{2} [-1 \quad 2 \quad -1]_{0..2}$$

$$\tilde{\mathbf{g}} = \frac{1}{8} [-1 \quad -2 \quad 6 \quad -2 \quad -1]_{-2..2}$$

- Obviously  $\tilde{\mathbf{h}}$  is a spline filter.  
The lifting scheme uses parameters  $\alpha = -\frac{1}{8}$  and  $\beta = \frac{1}{4}$



- Lifting scheme for the LeGall transformation

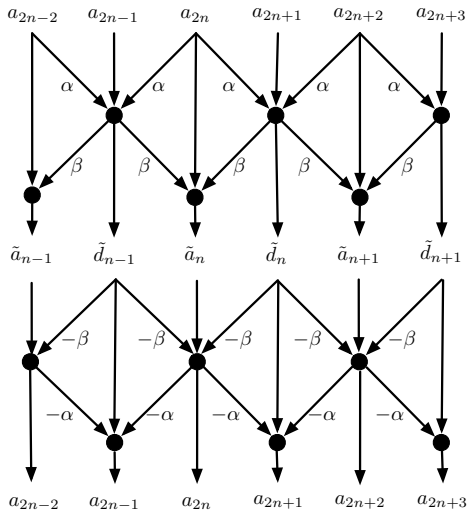


Figure: Lifting scheme for the LeGall transformation

- LeGall transformation

$$\begin{array}{cc}
 \text{analysis} & \text{synthesis} \\
 \tilde{d}_n = a_{2n+1} + \alpha (a_{2n} + a_{2n+2}) & a_{2n} = \tilde{a}_n - \beta (\tilde{d}_{n-1} + \tilde{d}_n) \\
 \tilde{a}_n = a_{2n} + \beta (\tilde{d}_{n-1} + \tilde{d}_n) & a_{2n+1} = \tilde{d}_n - \alpha (a_{2n} + a_{2n+2})
 \end{array}$$

- An interesting aspect of this filter pair is that it can be used to define and invertible *integer-to-integer* transformation – that is why it can be used for lossless compression!
- For analysis do

$$d_n^* = a_{2n+1} - \left[ \frac{1}{2} (a_{2n} + a_{2n+2}) \right], \quad a_n^* = a_{2n} + \left[ \frac{1}{4} (d_{n-1}^* + d_n^*) \right]$$

- and check that the synthesis transformation is given by

$$a_{2n} = a_n^* - \left[ \frac{1}{4} (d_{n-1}^* + d_n^*) + \frac{1}{2} \right], \quad a_{2n+1} = d_n^* + \left[ \frac{1}{2} (a_{2n} + a_{2n+2}) \right]$$